Honeywell

INSTALLATION MANUAL

BENDIX/KING®

KAP 140

FLIGHT CONTROL SYSTEM

MANUAL NUMBER 006-00991-0006 REVISION 6 OCT, 2002

WARNING

Prior the export of this document, review for export license requirement is needed.

COPYRIGHT NOTICE © 1998, 2002 Honeywell International Inc.

Reproduction of this publication or any portion thereof by any means without the express written permission of Honeywell is prohibited. For further information contact the Manager, Technical Publications, Honeywell, One Technology Center, 23500 West 105th Street Olathe KS 66061 Telephone: (913) 782-0400.

REVISION HISTORY

REV	DATE	CHANGES
4	August, 1998	Add unit versions
5	March, 2002	Add unit versions -2603, -5403, -7703
6	October, 2002	Add unit versions -2704, -5504, -7904

SECTION I GENERAL INFORMATION

Paragraph	Page
1.1[KAP[]40[FLIGHT[CONTROL[\$YSTEMS]]	1-1
1.2 EQUIPMENT DESCRIPTION	1 <u>- 2</u> 1 <u>- 1</u>
1.3 TECHNICAL CHARACTERISTICS	1⊟5 1⊟5 1⊟6
1.@_UNIT_NSTALLATION 1.@.TUnit_Flavors 1.@.ZInstallaton_Kits	1 ⊟8 1⊟8 1⊟9
1.5 ACCESSORIES REQUIRED BUT NOT SUPPLIED	1 <u>-11</u> 2 1 <u>-11</u> 2
SECTION II INSTALLATION	
Paragraph	Page
2.11 GENERAL INFORMATION	2-1
2.2 UNPACKING AND INSPECTING EQUIPMENT	2-1
2.3 EQUIPMENT INSTALLATION	2 H 1 2H 1 2H 2 2H 2
SECTION III OPERATION	
Paragraph	Page
3.[]GENERAL[]	3-[1

i

LIST OF ILLUSTRATIONS

Figure	e	Page
2-11 2-2 2-3 2-4 2-5 2-6 2-7	KC[] 40[DUTLINE[AND[]NSTALLATION[DWG[] KS[270C, [KS271C]&[KS[272C]WI[]]H[KM[275]]INSTALLATION[DWG[] KS[270C, [KS[271C, [KS[272C]WI[]]H[KM[277]]NSTALLATION[DWG[] KCM[] 00[]NSTALLATION[DWG[] KC[] 40[]NTERCONNECT[] KC140[COMBUTER[CABLE[ASSEMBLY[] CLUTCH[ADJUSTMENT[]	2-119 2-121 2-123 2-125 2-1217 2-139
	LIST OF TABLES	
Table		Page
2-110 2-120 2-130 2-140 2-150 2-160 2-170	KC[] 40[CONNECTOR[] 1401[PIN[F] NCTIONS[]. KC[] 40[CONNECTOR[] 1402[PIN[F] NCTIONS[]. KS[270C[CONNECTOR[PIN[F] NCTIONS[]. KS[271C[CONNECTOR[PIN[F] NCTIONS[]. CLUTCH[LOM[KEYING[]. KS[272C[CONNECTOR[PIN[F] NCTIONS[]. KCM[] 00[CONNECTOR[] 1010[FUNCTIONS[].	2 <u>11</u> 0 2 <u>11</u> 2 2 <u>11</u> 4 2 <u>11</u> 5 2 <u>11</u> 6 2 <u>11</u> 6 2 <u>11</u> 7

SECTION I

GENERAL INFORMATION

1.1 KAP 140 FLIGHT CONTROL SYSTEMS

The KAP 140 Flight Control System was developed in 1996 to provide up to two axis digital flight control to the entry level General Aviation market. This system is designed with several options for customer flexibility.

The KAP140 is offered as a single-axis (roll) and as a two-axis (pitch and roll) system. Manual Electric Trim can be added to any system. Autotrim can be added to a two-axis system. Altitude alerting is also availble for two-axis systems.



1.2 EQUIPMENT DESCRIPTION

The system modes for the KAP 140 Flight Control System is as follows:

Pitch Modes:	Vertical Speed (Default) (-5001 & up) †	
	Altitude Hold (-5001 & up) †	
	Glideslope (-5001 & up) †	
	Altitude Select Capture (-7501 & up) †	
Roll Modes :	Wings Level (Default)	
	Heading Select (-2501 & up) †	
	Nav (-2501 & up) †	
	Approach (-2501 & up) †	
	Reverse Localizer (-2501 & up) †	
Other:	Manual Trim	
	Automatic Trim (-5001 & up) †	
	Self Test	
	Control Wheel Steering	

The KAP 140 Flight Control System for a two axis with trim configuration consists of the following units:

UNIT	DESCRIPTION
KC 140	Flight Computer
KCM 100	Configuration Module
KS 270C	Pitch Axis Servo Actuator
KS 271C	Roll Axis Servo Actuator
KS 272C	Elevator Trim Servo Actuator
Supplied by Mid Continent	Rate Gyro
Supplied by SIGMA-TEK	DG
KM 275 or KM 277 (Total of 3 Required)	Servo Mount

[†] Number refers to flight computer version number

The KAP 140 Flight Control System for a two axis configuration consists of the following units:

UNIT	DESCRIPTION
KC 140	Flight Computer
KCM 100	Configuration Module
KS 270C	Pitch Axis Servo Actuator
KS 271C	Roll Axis Servo Actuator
Supplied by Mid-Continent	Rate Gyro
Supplied by SIGMA-TEK	DG
KM 275 or KM 277 (Total of 2 Required)	Servo Mount

The KAP 140 Flight Control System for a single axis configuration consists of the following units:

UNIT	DESCRIPTION
KC 140	Flight Computer
KCM 100	Configuration Module
KS 271C	Roll Axis Servo Actuator
KS 272C (Required if MET installed)	Elevator Trim Servo Actuator
KM 275 or KM 277 (1 required for roll; 2 required if MET installed)	Servo Mount
Supplied by Mid-Continent	Rate Gyro
Supplied by SIGMA-TEK	DG

NOTE: The KCS55A (HSI) can be installed in place of the DG in any of the systems above.

1.2.1 MODES OF OPERATION

MODE	FUNCTION PROVIDED	
Vertical Speed(VS)	Pitch default mode to hold and track vertical speed reference.	
Heading Select(HDG)	Roll command to the heading selected on the heading indicator (DG or HSI).	
NAV	Roll command to capture and track a navigation course provided by a NAV, GPS, or Localizer (w/o GS tracking).	
Approach(APR)	Roll and Pitch commands to capture and track LOC and GS Beams, VOR and GPS Approach course.	
Reverse Localizer(REV)	Roll command to capture and track a reverse LOC course.	
Altitude Hold(ALT)	Pitch command to hold a selected altitude.	
Vertical Trim	Function to modify engaged Altitude or Vertical Speed reference.	
Altitude Capture	Pitch Command to select and capture an altitude	
ROL	Roll default mode to hold wings level.	

1.3 TECHNICAL CHARACTERISTICS

1.3.1 System Technical Characteristics (In smooth air)

Maximum Bank Angles Limited to standard rate turn.

Heading Stability ± 2°

VOR Crosswind Compensation Up to 30° right or left

NAV/APR/REV Capture Capability

All angles

NAV/APR/REV Capture Computation Scheduled by beam closure rate

NAV Track Computation Scheduled by beam rate and deviation

APR/REV Track Computation Scheduled by beam rate and deviation

NAV Tracking System will track without large bank angles

keeping beam deviation to less than 1.0° of VOR. Actual performance will depend upon quality of VOR beam being received.

LOC Tracking System will track without large bank angles

keeping beam deviation to less than .25° of LOC. Actual performance will depend upon

quality of LOC beam being received.

Vertical Speed Stability ± 150 feet per minute

Altitude Range - 1000 to 35,000 ft

Altitude Hold Stability ± 50ft

Altitude Overshoot System will limit overshoot to less than 100

feet of selected altitude across the altitude range of the aircraft. When armed prior to

the capture point.

Vertical Trim <u>Mode Continuous</u> <u>Discrete</u>

ALH 500 FPM 20 Feet VS 300 FPM/SEC 100 FPM

Glideslope Capture Computation Scheduled by beam rate and deviation

Autopilot Disconnect Alerting External Sonalert, 500Ω audio with voice

messaging.

1.3.2 System Components Technical Characteristics

KC	4	40
NO	- 1	40

TSO Compliance: See Appendix A

Physical Dimensions (Nominal): Including Rack & Mating Connector

Width: 6.306 in (16.02 cm) Height: 1.665 in (4.229 cm)

Length: 11.35 in (28.829 cm) + 1.71 (4.343 cm)

(-7XXX)

11.35 in (28.829 cm) + .75 (1.91 cm)

(-2XXX, -5XXX)

Weight Including mounting rack and mating con-

nectors: (Nominal)

(-2XXX) 2.5 lbs. (1.1 kg) (-5XXX) 2.6 lbs. (1.2 kg) (-7XXX) 2.6 lbs. (1.2 kg)

Mounting: Panel with supplied rack

Mating Connectors: Subminiature

PN 030-01175-0000 37 pin PN 030-01176-0000 50 pin

20 Awg Crimp Contacts PN 030-01157-0011

Temperature: -45° C to +70° C

Altitude Range: -1,000 to 35,000 Ft

Power Inputs: +28VDC at 0.5A, 14V DC at 1.0A (nominal)

Power Outputs: +15VDC at 30ma

-15VDC at 30ma +5VDC at 80ma +4VDC at 50ma

Signal Inputs:

Directional Reference: 2 Wire Heading Datum, 550mV DC/Degree

Course Datum: 2 Wire Course Datum, 210mV DC/Degree

VOR/LOC Receiver: 15mV per Deg/VOR

LOC Energize Sense: Ground for LOC Enable and GPS Ap-

proach

Glideslope Receiver: 214mV/Deg

Revision 6, Oct 2002 CS:00991I06.IDU

Glideslope Valid: >180mV for Valid NAV Valid: >180mV for Valid Middle Marker Sense: 1 Wire, 3VDC Minimum for MKR on Pitch Trim Servo Voltage: 2 Wire, DC Differential voltage Trim Sense: 2 Wire, DC Differential voltage DG Valid: Open = Invalid, Ground = Valid Pitch Servo Drive: 2 Wire DC Differential, -10 to +10 VDC Roll Servo Drive: 2 Wire DC Differential, -10 to +10 VDC max. Pitch Trim Servo Drive: 2 Wire DC Differential, -10 to +10 VDC max. Servo Clutch Engages: 1 Wire, Ground to Engage(Each Axis) Roll Steering Valid: >11VDC=Valid, Open=Invalid 2 Wire DC differential voltage Roll Steering:

2 VDC/Degree

KS 270/1/2 C TSO Compliance: See Appendix A Physical Dimensions(Nominal): Length: 4.605 in (11.70 cm) without KM275 or KM277 4.675 in (11.87 cm) Height: Width: 3.925 in (9.97 cm) Weight: (Nominal) KS 270C: 2.5 lbs (1.09 kg) KS 271C: 2.2 lbs (1.00 kg) KS 272C: 2.1 lbs (0.95 kg) 1.0lbs (.45 Kg) KM 275 Servo Mount KM 277 Servo Mount Mounting: Two (2) AN 3 bolts Mating Connector: 030-03248-0000 Power Inputs: +28VDC at 4.0 amps Signal Inputs: -10VDC to +10VDC Servo Drive Command: Clutch Engage Signals: +28VDC(Active high input)

and Ground(Active low input)

-28VDC to +28VDC

-3VDC to +3VDC

Signal Outputs: Trim Voltage

Trim Sense

1.4 UNIT INSTALLATION

1.4.1 Unit Flavors

1.4.1.1 KC 140

The KC 140 is available in the following versions:

Part Number	Description
065-00176-2501,-2602, -2603	Roll Axis with Heading Select (1 Axis)
065-00176-2704	Roll Axis with Heading Select (1 Axis) and DC Roll Steering
065-00176-5001,-5101, -5201,-5302,-5402,-5403	Pitch and Roll system (2 Axis)
065-00176-5504	Pitch and Roll system (2 Axis) and DC Roll Steering
065-00176-7501,-7601, -7701,-7702,-7703,-7802	Pitch and Roll with Altitude Preselect
065-00176-7904	Pitch and Roll with Altitude Preselect and DC Roll Steering

1.4.1.2 KS 270C/271C/272C

The KS270C/271C/272C is available in the following versions:

Unit	Part Number	Speed	
KS 270C	065-00178-0100	3.6 RPM	
	065-00178-0200	2.4 RPM	
	065-00178-0300	4.7 RPM	
	065-00178-2100	3.6 RPM	
	065-00178-2200	2.4 RPM	
	065-00178-2300	4.7 RPM	
	065-00178-2400	1.2 RPM	
	065-00178-2500	1.9 RPM	
KS 271C	065-00179-0100	3.6 RPM	
	065-00179-0200	4.7 RPM	
	065-00179-0300	1.2 RPM	
	065-00179-0400	14.6 RPM	
	065-00179-0500	2.4 RPM	
	065-00179-0600	14.6 RPM	
KS 272C	065-00180-0400	2.4 RPM	
	065-00180-0600	14.6 RPM	
	065-00180-1400	22 RPM	
	065-00180-2700	3.6 RPM	
	065-00180-3500	4.7 RPM	

1.4.1.3 KM 275

The KM 275 is available in the following versions:

Part Number	Slip Clutch Used	Preset Torque (in-lbs)
065-0030-00	200-01678-0000 (Standard)	Variable
065-0030-02	200-02380-0000	Variable

1.4.1.4 KM 277

The KM 277 is available in the following versions:

Part Number	Slip Clutch Used	Preset Torque (in-lbs)
065-0041-00	200-02085-0000	Variable

1.4.1.5 KCM 100

The KCM 100 is available in the following versions:

Part Number	Description
071-00073-5000	Configuration Module

1.4.2 Installation Kits

1.4.2.1 KC 140

The KC 140 Installation Kit (PN 050-03375-0000/0001) consists of the following items:

KC140 -2XXX requires 050-03375-0000 Kit.

KC140 -5XXX and -7XXX require kit 050-03375-0001.

Symbol	CAS PN	Standard Description	UOM	-0000	-0001
ITM 1	030-01157-0011	SOCKET CRMP 20G	EA	80	80
ITM 2	030-02351-0023	CONN HOOD SIZE 37	EA	1	1
ITM 3	033-00230-0000	TELEPHONE JACK 4C	EA	1	1
ITM 4	047-10881-0001	MNTG RACK W/FIN	EA	1	1
ITM 5	047-11030-0002	END PLATE, RACK W HARDWARE	EA	1	1
ITM 6	089-02353-0001	NUT CLIP 6-32	EA	8	8
ITM 7	089-05903-0008	SCR PHP 4-40x1/2	EA	4	4
ITM 8	089-06012-0006	SCR FHP 6-32x3/8	EA	8	8
ITM 9	030-02351-0024	CONN HOOD SIZE 50	EA	1	1
ITM 10	089-06415-0006	SCR PHP 4-20x3/8	EA	4	4
J 1401	030-01175-0000	CONN SUB-D HSG 37S	EA	1	1
J 1402	030-01176-0000	CONN SUB-D HSG 50S	EA	1	1
ITM 11	076-02988-0002	RACK PORT W/FIN	EA	0	1
ITM 12	089-06636-0004	SCR FHP 4-40 X 1/4	EA	0	2
ITM 13	089-02147-0022	NUT LOCK 6-32	EA	2	2

1.4.2.2 KS 270C/271C/272C

The Installation Kit (PN 050-00398-0000) for the KS270C, KS 271C and KS272C consists of the following items:

Symbol	CAS PN	Standard Description	UOM	QTY
	030-01008-0000	LVR/PVT ASSY	EA	2
	030-01009-0000	HOOD CONN	EA	1
	030-01280-0001	CONNECTOR SOCKET	EA	16
	030-03248-0000	CONN RCPT HOUSING	EA	1
	057-01739-0000	INSTALLATION TAGS	EA	1
	089-05899-0003	SCR PHP 2-56X3/16	EA	4
	090-00731-0000	NUT ANCHOR CORNER	EA	2
	090-00348-0000	GUIDE PILOT/SCKT	EA	1
	090-00348-0001	GUIDE PILOT/SCKT	EA	1

1.4.2.3 KM 275 Servo Mount Installation Kit

The KM 275 Installation Kit (PN 050-01716-0000/0001) consists of the following items:

Refer to the appropriate STC installation manual to determine what version of kit, if any is required for a particular aircraft type.

Symbol	CAS PN	Standard Description	UOM	-0000	-0001
	047-04678-0001	CBL GRD	EA	2	
	047-06758-0000	PLATE ASSY	EA		1
	047-06760-0001	CABLE GUARD W/F	EA		1
	089-02344-0003	NUT LOCK 10-32	EA	2	
	089-07023-0005	SCR FLHP 8-32X5/16	EA		1
	089-08227-0008	WSHR FLT 10X.438	EA	2	
	090-00252-0004	PULLEY GUARD PIN	EA		4
	200-02428-0000	CAPSTAN IDLER	EA	1	

1.4.2.4 KCM 100 Configuration Module Installation Kit

The KCM 100 Installation Kit (PN 050-03245-0000) consists of the following items:

SYMBOL	CAS PART NBR	DESCRIPTION	[UOM]	-0000
_	030-01157-0011	SOCKET CRMP 20G	[EA]	10
_	030-02351-0005	HOOD/LVR ASSY SD E	[EA]	1
P 1010	030-01171-0000	CONN SUB-D HSG 9S	[EA]	1

1.4.2.5 KM 277 Servo Mount Installation Kit

The KM 277 does not require an installation kit.

1.4.3 Certification Diskettes

Installation of the KAP 140 Automatic Flight Control System requires the use of a certification diskette. This certification diskette contains files that define certain parameters that are uploaded to the KCM 100 configuration module and then used by the KC 140. These files are aircraft specific and each aircraft certification will have three separate files. The first eight characters of the filename for each of these files corresponds to the last eight digits of the 722–0XXXX–XXXX software archive number for that certification. The three digit extension will be one of the following: .CER, .DAT and .TXT. The .CER file is the certification file that contains the data that is uploaded to the KCM 100. The .DAT file lists the data that is uploaded to the KCM 100 in a decoded ("human readable") form. The .TXT file describes which aircraft the data pertains to and the expected aircraft harness strap code.

The following diskettes have been approved for use with the KAP 140 system:

Refer to the appropriate STC installation manual to determine which diskette is required for a particular aircraft type.

Part Number	Description
225-00028-XXXX	KAP 140 AFCS Certification Data
225-00035-XXXX	KAP 140 AFCS Certification Data

NOTE

Specify only the first 9 characters of the part number when ordering certification diskettes. The last 5 characters will be changed as software updates are made.

225-XXXXX -XXXX

1.5 ACCESSORIES REQUIRED BUT NOT SUPPLIED

Some of the following accessories are required, but not supplied as a part of the KAP 140 Flight Control System. Consult the appropriate STC data for requirements pertaining to your aircraft.

- A. KI 525A (PN 066-3046-XX) Horizontal Situation Indicator and installation kit (PN 050-01344-XXXX).
- B. KA 51B (PN 071-1242-XX) Compass Slaving Accessory and installation kit (PN 050-01928-XXXX).
- C. KMT 112 (PN 071-1052-XX) Compass Flux Valve and installation kit (PN 050-01361-0000).
- D. KG 102A (PN 060-0015-00) Directional Gyro and installation kit (PN 050-01410-XXXX).
- E. Sigma-Tek DG model 1U262-042-2 or 1U262-041-1.
- F. Mid Continent Turn Coordinator models 1394T100-10RZ, 1394T100-11RZ or 1394T100-12RZ

1.6 LICENSE REQUIREMENTS

None.

SECTION II INSTALLATION

2.1 GENERAL INFORMATION

This section contains general suggestions and information to consider before installation of the KAP 140 Flight Control System. Close adherence to these suggestions will assure optimum performance from the equipment. Specific installation requirements are contained in the STC Installation Manual that pertains to the particular type of aircraft which the equipment is to be installed.

NOTE

"The conditions and tests required for TSO approval of this article are minimum performance standards. It is the responsibility of those desiring to install the article either on or within a specific type or class of aircraft to determine that the aircraft installation conditions are within the TSO standards. If not within the TSO standards, the article may be installed only if further evaluation by the applicant documents an acceptable installation and is approved by the Administrator."

2.2 UNPACKING AND INSPECTING EQUIPMENT

Exercise extreme care when unpacking the equipment. Make a visual inspection of the unit for evidence of damage incurred during shipment. If a claim for damage is to be made, save the shipping container to substantiate the claim. The claim should be promptly filed with the transportation company. It would be advisable to retain the container and packaging material after all equipment has been removed in the event that equipment storage or reshipment should become necessary.

2.3 EQUIPMENT INSTALLATION

2.3.1 Avionics Cooling requirements for Panel Mounted Equipment

The greatest single contributor to increased reliability of all modern day avionics is to limit the maximum operating temperature of the individual units whether panel mounted or remote mounted. While modern day individual circuit designs consume much less electrical energy, watts per cubic inch dissipated within the avionics unit remains much the same due to high density packaging techniques utilized. Consequently, the importance of providing cooling to the avionics stack is still with us today.

While the KC140 does not require forced air cooling, the combined heat load of several units operating in a typical avionics location will significantly degrade the reliability of the avionics if provisions for cooling are not incorporated in the initial installation. Failure to provide cooling to the equipment will lead to increased avionics maintenance costs and may also void the AlliedSignal Inc warranty.

2.3.2 KC 140 Installation

The KC 140 installation will conform to standards designated by the customer, installing agency, and existing conditions as to the unit location and type of installation. However, the following instructions will assure a more satisfactory performance from the equipment. Mounting locations are provided near the front and rear of the mounting rack. It is necessary to utilize both the front and rear mounting locations when installing the KC140 mounting rack.

CAUTION

For two axis installations the static port on the rear of the KC140 is designed to float to ensure alignment with the static port on the mounting rack. Do not attempt to tighten the mounting screws for the KC140 static port.

WARNING

FOR TWO AXIS INSTALLATIONS REMOVAL OF THE KC 140 FROM ITS MOUNTING RACK IN THE AIRCRAFT PANEL OPENS THE STATIC AIR SYSTEM TO THE AIRCRAFT CABIN. AFTER REINSTALLATION OF THE KC140, VERIFY THAT THE STATIC AIR SYSTEM COMPLIES WITH F.A.R. 91.411.

NOTE

The following information is provided in the event that the o-ring on the KC140 static port requires replacement. The o-ring is 70 durometer EPDM material, AS568A-006 size. The AlliedSignal part number is 187-01004-0013. The o-ring should be greased with AlliedSignal part number 016-01210-0000, Dow Corning 55 o-ring Lubricant (Mil-G-4343) or equivalent grease.

2.3.3 Installation Procedures

Refer to the appropriate STC installation manual.

The first time the AFCS is turned on in a new installation, the FCC must be configured through an RS232 interface. The FCC provides an RS232 interface for diagnostic and installation capabilities.

2.3.3.1 RS232 Interface

The RS232 interface to the computer is through a Remote Terminal Interface (RTI) connector located in the cockpit. A terminal or PC with terminal emulation must be connected to this port. Set the communication parameters as follows: 9600 baud rate, no parity, 8 data bits, and one stop bit. IMPORTANT: System configuration cannot be accomplished without using the RTI. Use computer cable assembly PN 155-02794-0001, to connect PC communications port to the RTI connector.

2.3.3.1.1 RTI Main Menu

Apply power to the flight computer. Preflight test will attempt to run, but will fail if the unit has not been previously installed. After a few seconds, the main menu should appear on the terminal. If it does not, press CTRL-W to refresh the screen. If communications cannot be established, check the RS232 interconnect and terminal setup.

2.3.3.1.2 RTI Menu Operation

The main menu provides selection of entering diagnostic mode, displaying the error log, displaying the Software Identification number, or configuring the installation. The following sections provide specific instructions on using these capabilities to perform the required installation and ground checkout procedures. NOTE: Selection of diagnostics will inhibit normal operation of the flight computer.

2.3.3.1.3 Configuration Procedure

1. To configure/install the flight computer, the following must be completed:

AFCS system harness installation checked (ring test).

Aircraft ground power applied.

Avionics power applied.

Sensors operating (Turn Coordinator, DG/HSI, nav's).

RS232 communications established with FCC.

The remote terminal should now display the following menu:

System Mode: Normal (or Diagnostics)

KC 140 Flight Computer

D - Diagnostics

L - Error Log

S - Display SW ID

N - Installation

Press any key for desired option:

2. Press "N" to enter the installation menu. The terminal should display a menu with, "1. Installation Setup". Press "1". Now the terminal should display the message: "Upload installation file or press <ESC> to abort". Use the terminal program of the PC to send the correct certification file. When the file transfer is complete, the terminal should display the message, "Installation data have been saved in nonvolatile memory". Press <CR> to return to the installation options page. Set the audio volume to the desired value and select the other options, as appropriate. The options displayed will depend upon the aircraft certification and the version of the FCC. The following describes all available options and their meaning.

NOTE

The Certification files for existing KAP140 certifications is distributed on <code>diskette</code> <code>from</code> <code>flactory</code> <code>[See</code> <code>Section</code> <code>]</code> .4.3). <code>[Insert</code> <code>[Insert</code> <code>[Insert</code> <code>]</code> .4.3). <code>[Insert</code> <code>[Insert</code> <code>[Insert</code> <code>[Insert</code> <code>Insert</code> <code>Insert</code>

A volume setting of "0" is the minimum level and "7" is the maximum.

A "1" for "Voice Msg Enabled" will enable voice messages for AP disconnect and altitude alerting, in addition to the normal tones produced for these events. (This option is not available on the -2501 (MOD1) -5XX1, -7XX1 versions of the KC140).

A "1" for "Remote Baro" will cause the system to use the baro set input from the altimeter and disable the ability to change baro set from the FCC (although it will still display baro set when the BARO button is pressed).

A "1" for "HSI/DG" will select the proper operation for a system with an HSI. A "0" is the proper selection for a DG installation.

A "1" for "Trim Installed" will configure the system to provide Manual Electric Trim. Autotrim will also be provided in a two-axis system.

A "1" for "NAV Force Valid" will cause the system to always treat the NAV deviation as valid, ignoring the NAV Valid input. This option should be chosen only if NAV Valid is not available in the installation.

After selecting the desired options, press <CR> to return to the main menu. Now cycle power
to force the system to perform a preflight test. The PFT should now pass. If not, check the error
log and determine problem.

2.3.3.2 System Offset Adjustments

After the system has been installed, sensor offsets need to be nulled for optimum system performance. These adjustments are stored in the configuration module and may be repeated, as desired, without performing installation setup again. Adjustments of the pitch and roll axis nulls are made with the single-turn potentiometer on the front panel of the flight computer (right-hand side of the display).

WARNING

A MINIMUM OF 10 MINUTES SHOULD BE ALLOWED FOR THE FCC TO FULLY COMPUTE AND STORE VERTICAL ACCELERATION NULL DATA TO THE KCM CONFIGURATION MODULE. WHEN INSTALLING A NEW FCC AND/OR A NEW KCM 100 CONFIGURATION MODULE, THE FCC **AUTOPILOT** SYSTEM MUST ESTABLISH VERTICAL ACCELERATION NULLS BEFORE ANY MANUAL ADJUSTMENTS CAN BE MADE.

Apply power to the aircraft and to the KAP 140 autopilot system, allow the FCC to store the vertical acceleration offsets to the KCM 100 configuration module. The aircraft should be stable during the alignment, with no movement or jarring. No FCC modes should be engaged until the alignment process has been completed.

This procedure is required whenever the FCC and/or KCM 100 configuration module is/are removed from the aircraft for servicing and reinstalled, or whenever either component is replaced.

NOTE

For the roll and pitch axis null adjustments, adjust the pot until 0 \pm .020 volts DC is measured across the servo drive pins D and L of the roll servo and the pitch servo harness connectors. This is accomplished as follows: First, allow the FCC to pass pre-flight test; then unplug the servo connector from the aircraft harness. Next apply an aircraft ground to pin K of the harness connector. Now connect the digital multimeter across the harness connector pins D and L to monitor the servo drive voltage.

- 1. Engage the autopilot by pressing the "AP" button on the FCC. The default ROL mode must be selected, i.e. the HDG, NAV, or APR modes are not engaged. Using a DMM, measure the DC voltage across pins D and L of the roll servo harness connector. Adjust the pot until a value of 0 ± .020 volts is measured. If you reach the end of the pot travel before nulling the servo drive, disengage the autopilot, turn the pot fully to the opposite stop, and re-engage the autopilot. The roll null adjustment emulates a four-turn pot by allowing this method of "resetting" the pot adjustment range. This adjustment compensates for offsets in the roll axes, including the turn indicator. Continue turning the pot to null the voltage.
- 2. In a two axis system, the pitch axis must also be adjusted. This is accomplished by pressing the "ALT" button (engaging the altitude hold mode). Now, press and hold the "ALT" button (engaging the vertical speed mode VS) and then press and hold the "DN" button while still pressing and holding the "ALT" button. In this state, the pot should be used to adjust the pitch servo drive to a null. Using a DMM, measure the DC voltage across pins D and L of the pitch servo harness connector. Adjust the pot until a value of $0 \pm .020$ volts is measured.
- 3. Reconnect the servo harness connectors(s) to the servo(s) before proceeding any further.

The rest of the sensor offsets are compensated by a different method, using the remote terminal interface. From the top-level menu on the terminal, enter the installation menu by pressing "N". Now press "2" and "ENTER" to enter the Installation Offset page. From this page, the remaining offsets can be compensated. For each parameter listed, after entering the associated number, zero the input to the flight computer and press "ENTER". This can be done without engaging the autopilot. The null values will be stored in the configuration module and used to compensate the input value when the autopilot is engaged. The following paragraphs detail this procedure.

Turn the heading bug (and course pointer, if HSI installation) to the lubber line. For a KI 525A, alignment should be done with the aircraft or compass card pointing north(Slew Compass). Select Heading Datum on the installation offset page and press "ENTER". Do the same for Course Datum. This compensates for offsets in the DG/HSI.

Using a test generator, create a valid VOR signal and adjust until the deviation displayed on the CDI or HSI is centered. Select VOR Deviation on the installation offset page and press "ENTER". This compensates for offsets in the VOR deviation signal. If a GPS is installed, select GPS and perform the same procedure for GPS deviation. Select an ILS frequency and perform the same procedure for the Localizer deviation.

In a two-axis installation, create a valid Glideslope signal and null the deviation display. Now select the GS Deviation and press "ENTER". This will compensate for any offsets in the glideslope tracking.

This completes the installation offset adjustments. Now return to the top-level menu by pressing "ENTER" twice, to prevent accidental changes in the offset parameters.

2.3.3.2.1 Display Brightness adjustments

The display uses a photocell to automatically adjust the brightness under a wide range of ambient conditions. The unit contains a default brightness curve to track ambient changes. If necessary, the brightness curve of the display can be adjusted. The display brightness adjustment is accomplished by engaging the autopilot and keeping the AP button pressed. While holding the AP button, adjust the pot to obtain the desired display brightness. NOTE: This adjustment controls two independent settings -- at moderate to bright ambient conditions, it controls the slope of the brightness vs. ambient curve. In darker ambient conditions, it controls the minimum display brightness. Therefore, for optimum alignment, first adjust the display in a dark ambient to achieve the desired brightness under these conditions. Then adjust it again, as required, under moderate-to-full brightness ambient conditions.

2.3.3.2.2 Switch Backlighting adjustments.

The switch backlighting brightness is controlled by the dim bus input to the flight computer. However, the minimum backlighting level can be adjusted, if desired. This adjustment is made by disengaging the autopilot with the AP switch while continuing to hold the switch. The adjustment is also made with the front panel pot.

2.3.3.3 Ground Checkout Procedure

If the system has been successfully adjusted as described above, the following ground checkout should be performed.

Engage the autopilot in the HDG mode and move the heading bug left and right of the lubber line. The control wheel should follow the heading bug direction and should stop moving when the bug is under the lubber line.

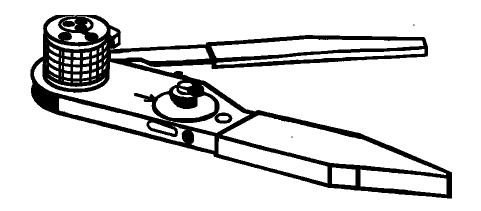
Engage APR mode with an ILS signal and watch for proper response to deviations in LOC (and GS in a two-axis system). If a GPS is installed, select this sensor and use NAV mode to check autopilot response to the GPS deviation.

A fly right deviation should cause the control wheel to turn to the right, while a fly left deviation should cause the control wheel to turn left. For the GS, a fly up deviation should cause a rearward control motion; a fly down deviation should cause the control to move forward. It is not necessary to stop or center the control wheel with the deviations, since the offset adjustment procedure has already been performed.

In a two-axis system, engage VS (default) mode and check for rearward control wheel movement after pressing the UP button twice (to change the VS reference) Check for nose down control by pressing the DN button three times (to establish a nose down VS reference). The control wheel should now move forward. Press CWS on the control wheel and check that the control wheel stops moving. Release CWS and the control wheel should still not move in the pitch axis. If trim is installed, check autotrim operation by slowly pushing the control wheel forward. After a few seconds, the trim should run in the UP direction. Now, slowly pull back on the wheel and check for trim in the DN direction after a few seconds.

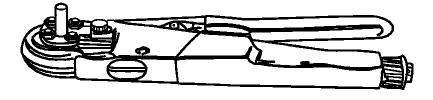
If trim is installed, check Manual Electric Trim by pressing the switches in the UP direction (with ARM). The trim should run in the UP direction. Check again with the DN switch (and ARM). Now

press the UP switch without pressing ARM and check for no trim response. Do the same with the DN switch. NOTE: An active UP or DN switch without ARM will trip a latent switch failure monitor after three seconds. For SW MOD 01/05 software or later, "PT" will be annunciated on the KC 140 and MET operation will be disabled until all three MET switch inputs are inactive. For earlier versions, "PT" will be annunciated on the KC 140 and MET operation will be disabled until the fault is cleared and unit power is cycled.



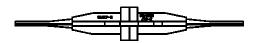
CRIMPING TOOL AlliedSignal P/N 005-02012-0017 Daniels Mfg. P/N M22520/1-01 Positronic P/N 9501

POSITIONER AlliedSignal P/N 005-02012-0018 Daniels Mfg. P/N M22520/1-03 Positronic P/N 9502-1

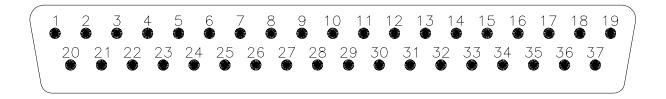


CRIMPING TOOL P/N: 005-02012-0021 BUCHANAN P/N 612118 POSITRONIC P/N: 9508

POSITIONER P/N: 005-02012-0023 BUCHANAN P/N 612513 POSITRONIC P/N: 9502-7



INSERTION/EXTRACTION TOOL P/N: 005-02012-0025 AMP P/N 91067-2 MIL SPEC P/N: M24308/18-12

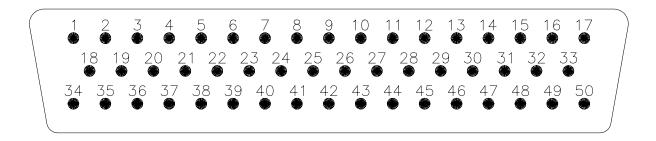


FACE VIEW INPUT=> OUTPUT=<

TABLE 2-1 KC 140 CONNECTOR J1401 PIN FUNCTIONS

Pin	I/O	Description
1	<	ROLL CLUTCH
2	>	HDG DATUM +
3	>	ROLL RATE -
4	<	CFG_+5V
5	>	ROLL SERVO VALID
6	<	AUDIO ALERT
7	>	ILS
8	<>	CFG DATA
9	>	AP DISCONNECT
10	>	RATE VALID
11	>	DG VALID
12	>	DIM BUS
13	<	CFG ENABLE
14	>	AUDIO POWER
15	>	CHASSIS GROUND
16	>	AIRCRAFT POWER
17	>	STRAP 5
18	<	ROLL SERVO CMD
19	<	ROLL SERVO CMD REF
20	<	TONE ALERT
21	>	ROLL RATE +
22	>	NAV + FLAG
23	>	NAV - FLAG
24	>	NAV DEV + LEFT
25	>	NAV DEV + RIGHT

Pin	I/O	Description
26	>	CWS
27	>	CRS/HDG DATUM REF
28	<	TXD RS232
29	>	RXD RS232
30	<	CFG CLK
31	>	STRAP 1
32	>	STRAP 2
33	>	STRAP 3
34	>	STRAP 4
35	>	GROUND
36	>	STRAP 6
37	<	VISUAL ALERT



FACE VIEW INPUT=> OUTPUT=<

TABLE 2-2 KC 140 CONNECTOR J1402 PIN FUNCTIONS

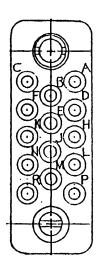
Pins	I/O	Description
1	<	TRIM CLUTCH
2	>	TRIM VOLTAGE -
3	>	C2
4	>	TRIM VOLTAGE -
5	>	C4
6	>	TRIM SENSE +
7	<	PITCH SERVO CMD
8	<	PITCH CLUTCH
9	>	GS + UP
10	>	GS + DN
11	>	A1
12	>	GS - FLAG
13	>	A2
14	>	A4
15	>	CHASSIS GROUND
16	>	BARO SET
17	>	CRS DATUM +
18	<	DG +15 VDC
19	<	DG -15 VDC
20	>	B4
21	>	C1
22	>	TRIM UP

23		Description	
	>	TRIM SENSE	
24	<	PITCH SERVO CMD REF	
25	>	TRIM ARM	
26	>	GPS SELECT	
27	>	TRIM DOWN	
28	>	PITCH SERVO VALID	
29	>	D4	
30	>	STALL WARNING	
31	>	GS + FLAG	
32	<	TRIM SERVO CMD	
33	>	B1	
34	>	B2	
35	>	XPNDR REF	
36	<	TRIM SERVO CMD REF	
37	<	BARO REF SUPPLY	
38	>	MIDDLE MARKER	
39		SPARE	
40	>	ROLL STEER VALID ***	
41	>	ROLL STEER + ***	
42	>	ROLL STEER - ***	
43	>	PFT CONTROL EN	
44	<	TRIM FAIL ANN	
45	>	FLAPS + UP SENSE	
46	>	FLAPS + DN SENSE	
47	>	TACH + **	
48	>	TACH - **	
49	>	AUDIO LOAD RESISTOR*	
50		SPARE	

^{*}For -2501 units, Mod 1 and above only

^{**}For -5201, -5402, -7702 units only

^{***}For XX04 units only

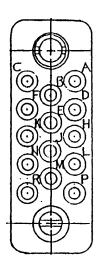


P270C1

Α	TACH +*
В	VALID TP
С	POWER GND
D	COMMAND REF
Е	AP DISCONNECT
F	CLUTCH LOW
Н	+28V
J	TRIM SENSE +
K	VALID BAR
L	COMMAND
М	VALID TP
N	CHASSIS GROUND
Р	VREF (REFERENCE VOLTAGE), TACH -*
R	TRIM SENSE -

^{*}For -2X00 servos only

TABLE 2-3 KS 270C CONNECTOR PIN FUNCTIONS



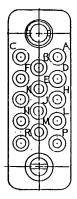
P271C1

Α	TACH TEST
В	VALID TP
С	POWER GND
D	COMMAND REF
Е	AP DISCONNECT
F	CLUTCH LOW
Н	+28V
J	SPARE
K	VALID BAR
L	COMMAND
М	VALID TP
N	CHASSIS GROUND
Р	VREF (REFERENCE VOLTAGE)
R	SPARE

TABLE 2-4 KS 271C CONNECTOR PIN FUNCTIONS

TOP[VERSION[#	CLUTCH[LOW]CONNECTION[PIN]LETTER)
065⊟00180⊟0400	В
065⊟©0180⊟©600	Κ
065⊟00180⊟11400	Р
065⊟00180⊟2700	F
065⊟00180⊟3500	M

TABLE[2H5[CLUTCH[LQW[KEYING

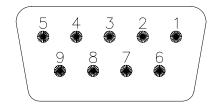


*P272C1

*[SEE]TABLE[2]B[FOR[CLUTCH]LOW[KEYING[PER[UNI]]]VERSION[NUMBER]

A DISABLE BAR B SEE[TABLE]] C POWER GND D COMMAND REF E AP DISCONNECT F SEE[TABLE]] H +28V J MOTOR FEEDBACK 1 K SEE[TABLE]] L COMMAND M SEE[TABLE]] N CHASSIS GROUND P SEE[TABLE]] R MOTOR FEEDBACK 2		
C POWER GND D COMMAND REF E AP DISCONNECT F SEE[TABLE] H +28V J MOTOR FEEDBACK 1 K SEE[TABLE] L COMMAND M SEE[TABLE] N CHASSIS GROUND P SEE[TABLE]	Α	DISABLE BAR
D COMMAND REF E AP DISCONNECT F SEE[TABLE] H +28V J MOTOR FEEDBACK 1 K SEE[TABLE] L COMMAND M SEE[TABLE] N CHASSIS GROUND P SEE[TABLE]	В	SEE[TABLE[]
E AP DISCONNECT F SEE[TABLE] H +28V J MOTOR FEEDBACK 1 K SEE[TABLE] L COMMAND M SEE[TABLE] N CHASSIS GROUND P SEE[TABLE]	С	POWER GND
F SEE[TABLE] H +28V J MOTOR FEEDBACK 1 K SEE[TABLE] L COMMAND M SEE[TABLE] N CHASSIS GROUND P SEE[TABLE]	D	COMMAND REF
H +28V J MOTOR FEEDBACK 1 K SEE[TABLE[] L COMMAND M SEE[TABLE[] N CHASSIS GROUND P SEE[TABLE[]	Е	AP DISCONNECT
J MOTOR FEEDBACK 1 K SEE[TABLE] L COMMAND M SEE[TABLE] N CHASSIS GROUND P SEE[TABLE]	F	SEE[TABLE[]
K SEE[TABLE] L COMMAND M SEE[TABLE] N CHASSIS GROUND P SEE[TABLE]	Н	+28V
L COMMAND M SEE[TABLE] N CHASSIS GROUND P SEE[TABLE]	J	MOTOR FEEDBACK 1
M SEE[TABLE[] N CHASSIS GROUND P SEE[TABLE[]	K	SEE[TABLE[]
N CHASSIS GROUND P SEE[TABLE[]	L	COMMAND
P SEE[TABLE[]	М	SEE[TABLE[]
	N	CHASSIS GROUND
R MOTOR FEEDBACK 2	Р	SEE[TABLE[]
	R	MOTOR FEEDBACK 2

TABLE 2-6 KS 272C CONNECTOR PIN FUNCTIONS



FACE VIEW INPUT=> OUTPUT=<

Pin	I/O	Description
1	>	+ 5VDC IN
2	<>	GROUND
3	>	CFG ENABLE
4	>	CFG CLOCK
5	<>	CFG DATA
6		SPARE
7		SPARE
8		SPARE
9		SPARE

TABLE 2-7 KCM 100 CONNECTOR J1010 PIN FUNCTIONS

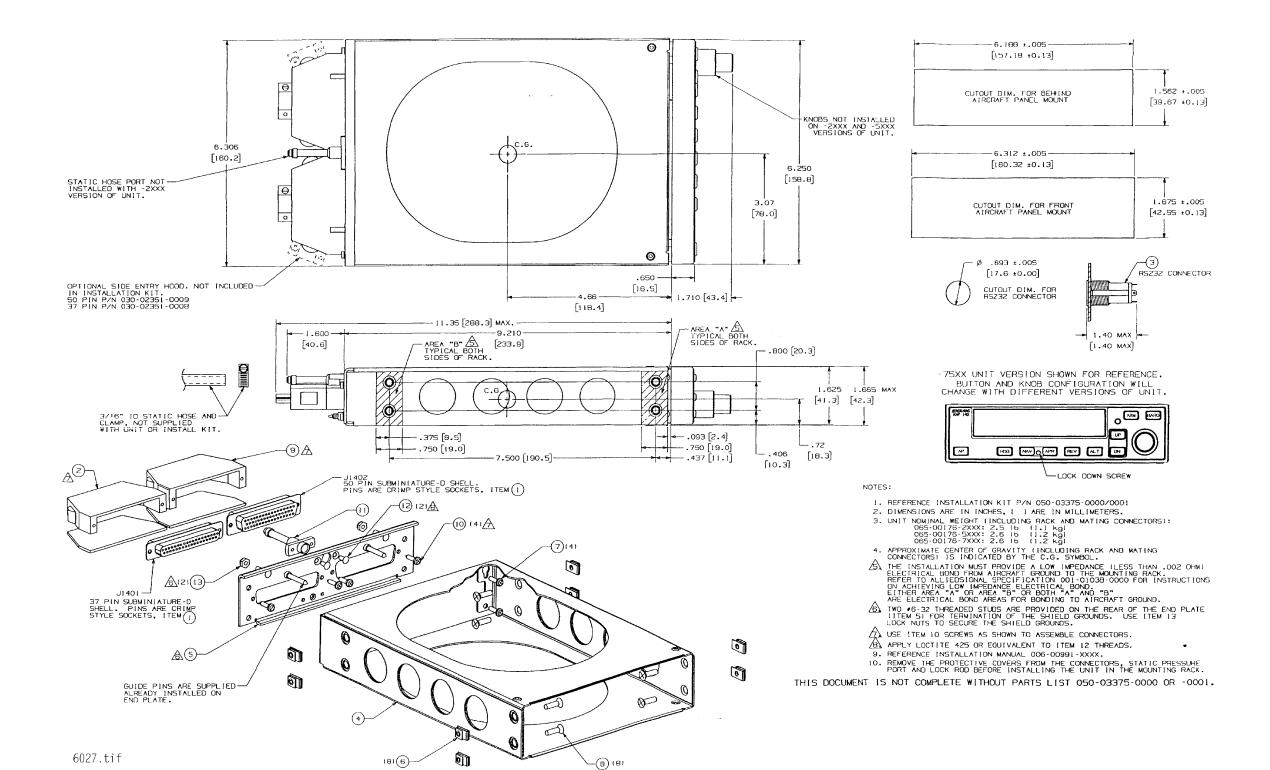


FIGURE 2-1 KC 140 OUTLINE AND INSTALLATION DRAWING (Dwg No 155-06027-0001, Rev 4) (Sheet 1 of 1)

Revision 6, Oct 2002 CS:00991I06.IDU

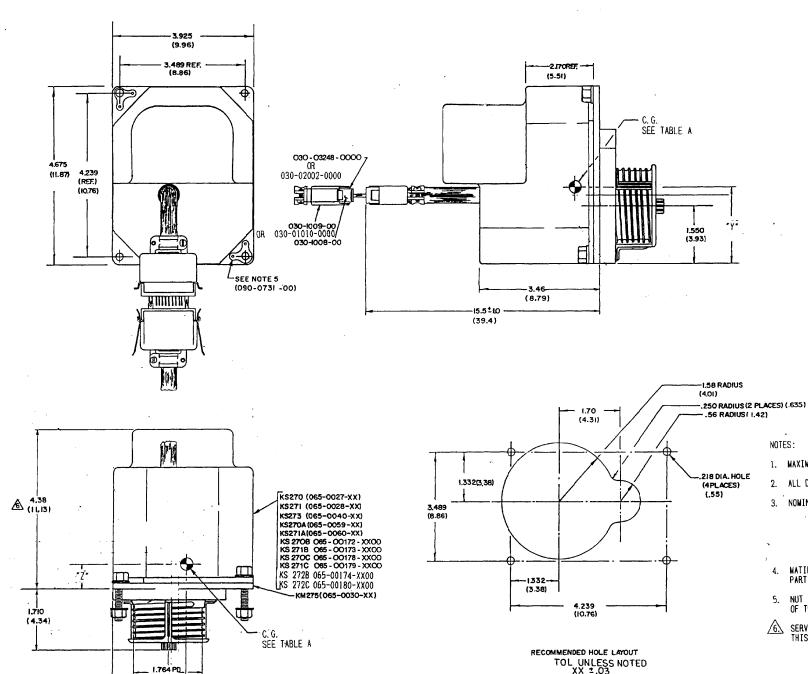


FIGURE 2-2 KS 270C, KS271C & KS 272C WITH KM 275 INSTALLATION DRAWING (Dwg No 155-05161-0000, Rev AC) (Sheet 1 of 1)

Revision 6, Oct 2002 CS:00991I06.IDU

5161AC00.TIF

_1.550 _ (3.93)

SERVO WITH KW275 C.G. LOCATION TOL. +. 12(.30) ~X~ *Z* KS270 KS270A KS271 KS271A KS273 2. 05 (5. 21) 2. 05 . 43 (5. 21) (1. 09) KS270B KS270C 1. 95 (4. 95) 2. 00 . 85 (5. 08) (2. 16) KS271B KS271C 2. 00 (5. 08) 1. 80 (4. 57) . 71 (1. 80) KS272B KS272C 1.85 (4.70) 2. 05 (5. 21)

TABLE A

- 1. MAXIMUM CABLE TRAVEL ±7.0 INCHES.
- 2. ALL DIMENSIONS IN () ARE IN CENTIMETERS.
- 3. NOMINAL WEIGHT KS 270 2.2 LBS. (1 KG) KS 272 2.2 LBS. (1 KG)
 KS 271 2.2 LBS. (1 KG) KS 270A 2.6 LBS. (1.18 KG)
 KS 275 1.0 LB. (.45 KG) KS 271A 2.4 LBS. (1.09 KG)
 KS 270B 2.5 LBS. (1.13 KG) KS 270C 2.5 LBS. (1.13 KG)
 KS 271B 2.2 LBS. (1.0 KG) KS 271C 2.2 LBS. (1.0 KG)
 KS 272B 2.1 LBS. (.95 KG) KS 272C 2.1 LBS. (.95 KG)
- MATING CONNECTOR HOOD AND LEVER-PIVOT ASSY ARE PART OF THE 050-00398-0000 OR 050-01450-0001.
- 5. NUT ANCHOR CORNER PLATES MAY BE USED IN PLACE OF NUTS AT THE OPTION OF THE INSTALLER.
- SERVO LENGTH 4.605 \pm .Q3 (11.70 \pm .Q8) WITHOUT KM275. THIS LENGTH INCLUDES THE PINION GEAR.

XXX2.015

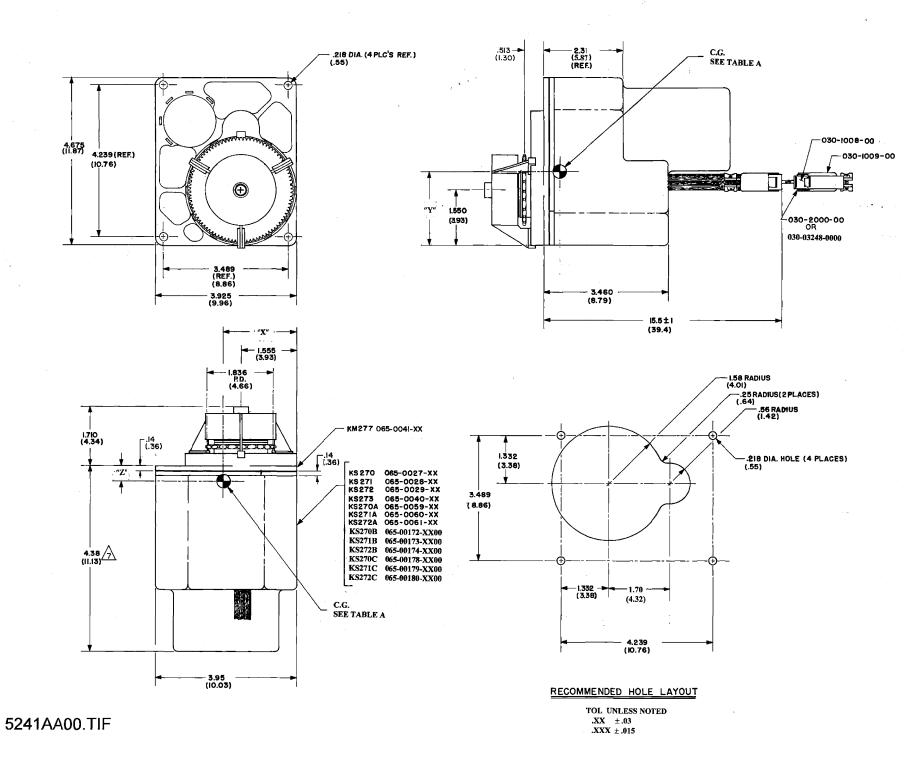
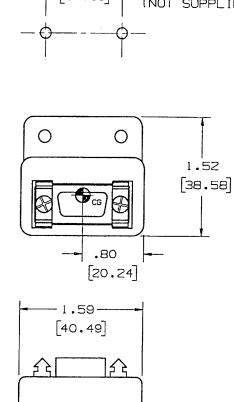


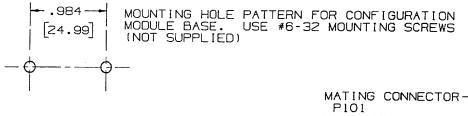
FIGURE 2-3 KS 270C, KS 271C, KS 272C WITH KM 277 INSTALLATION DRAWING (Dwg No 155-05241-0000, Rev AA) (Sheet 1 of 1)

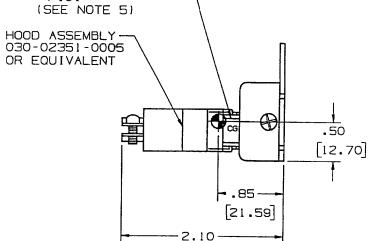
Revision 6, Oct 2002 CS:00991I06.IDU

TABLE A

JADLE A .								
SERVO WITH KW277 C.G. LOCATION TOL. ± .12 (.30)								
SERVO	″X″	"Y"	″Z″					
KS270 KS270A KS271 KS271A KS272 KS272A KS273	2. 05 (5. 21)	2. 05 (5. 21)	. 4 3 (1. 09)					
KS270B KS270C	2. 02 (5. 13)	2. 10 (5. 33)	1. 08 (2. 74)					
KS271B KS271C	1. 90 (4. 83)	2. 10 (5. 33)	1. 08 (2. 74)					
KS272B KS272C	1. 90 (4. 83)	2. 08 (5. 28)	1.00 (2.54)					







[53.31]

60080100.TIF

NOTES:

- 1. ALL DIMENSIONS IN INCHES [MILLIMETERS].
- 2. DENOTES CENTER OF GRAVITY.
 C.G. IS THE CENTER OF GRAVITY OF UNIT WITH MATING CONNECTOR AND HOOD ASSEMBLY.
- 3. WEIGHT (INCLUDING MATING CONNECTOR AND HOOD ASSEMBLY):

0.10 LBS. (.0454 kg)

- 4. REFERENCE: INSTALLATION KIT W/CRIMP CONTACTS 050-03245-0000. PRODUCT STRUCTURE DIAGRAM 000-00917-0000.
- 5. MATING CONNECTOR (PIOI):

 CRIMP 030-01171-0000 OR EQUIVALENT
 030-01157-0011 OR EQUIVALENT (CONTACTS)

FIGURE 2-4 KCM 100 INSTALLATION DRAWING (Dwg No 155-06008-0000, Rev 1) (Sheet 1 of 1)

(Sheet 1 of 1)

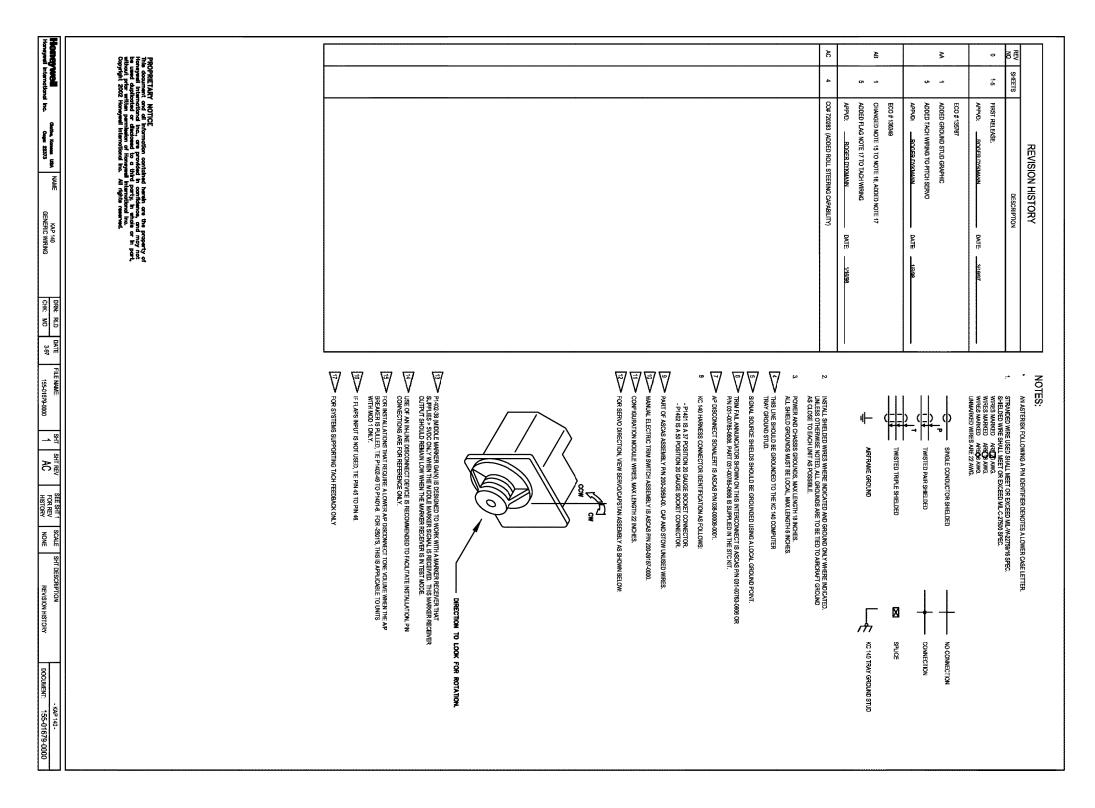


FIGURE 2-5 KC 140 INTERCONNECT (Dwg No 155-01679-0000, Rev AC, Sheet 1 of 5)

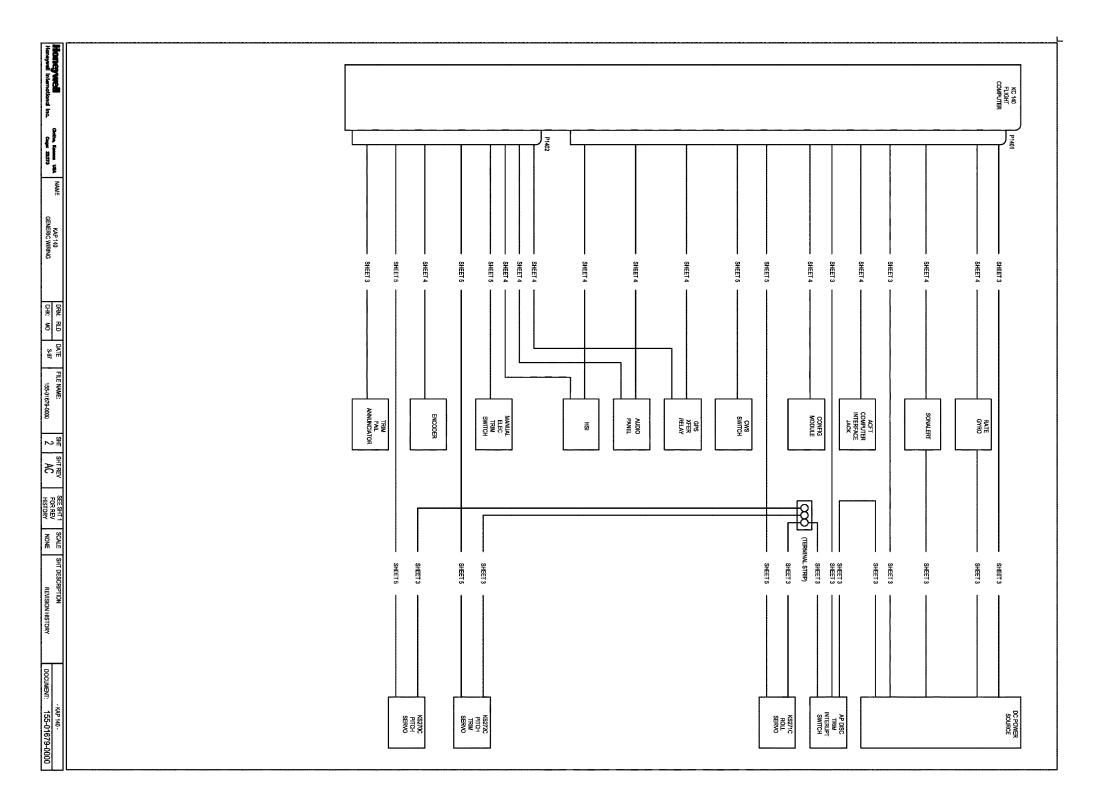


FIGURE 2-5 KC 140 INTERCONNECT (Sheet 2 of 5)

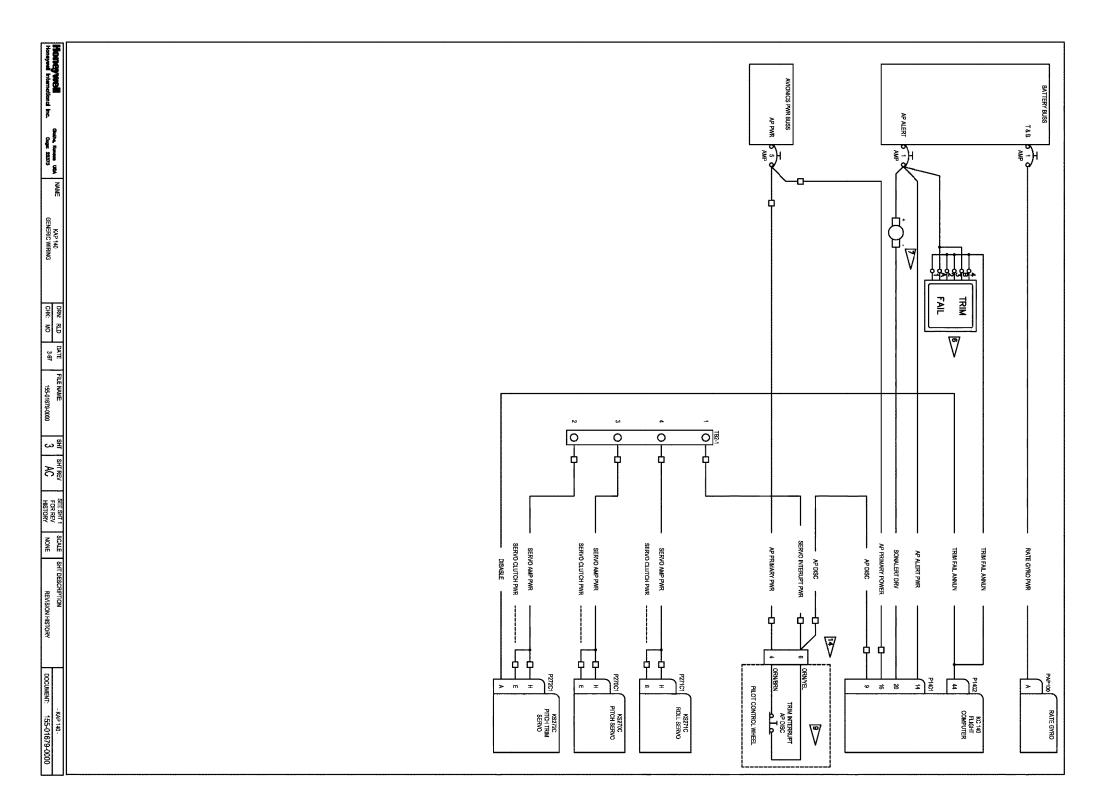


FIGURE 2-5 KC 140 INTERCONNECT (Sheet 3 of 5)

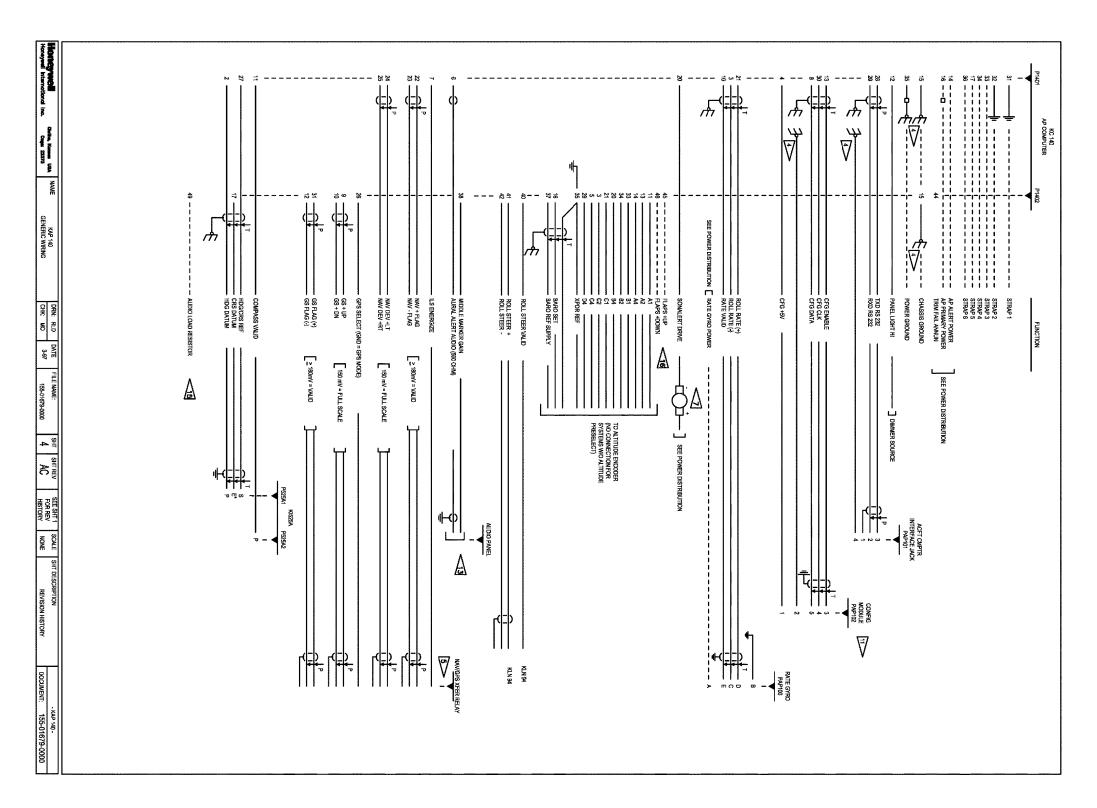


FIGURE 2-5 KC 140 INTERCONNECT (Sheet 4 of 5)

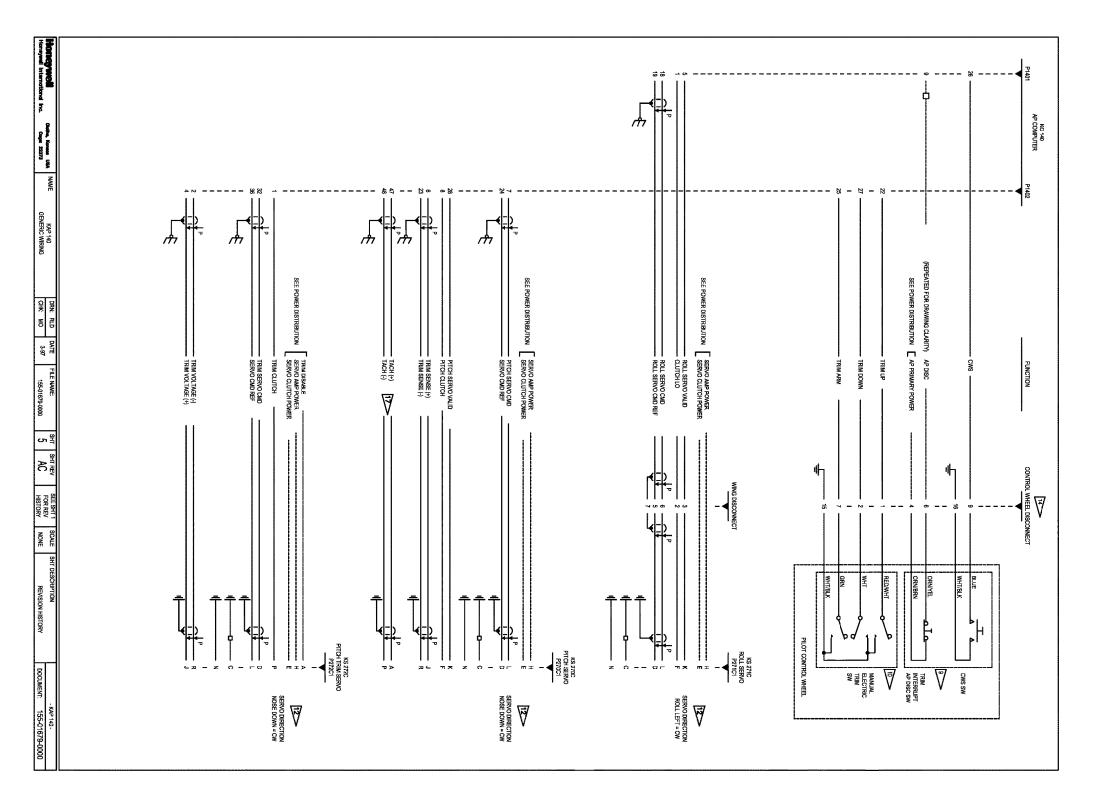
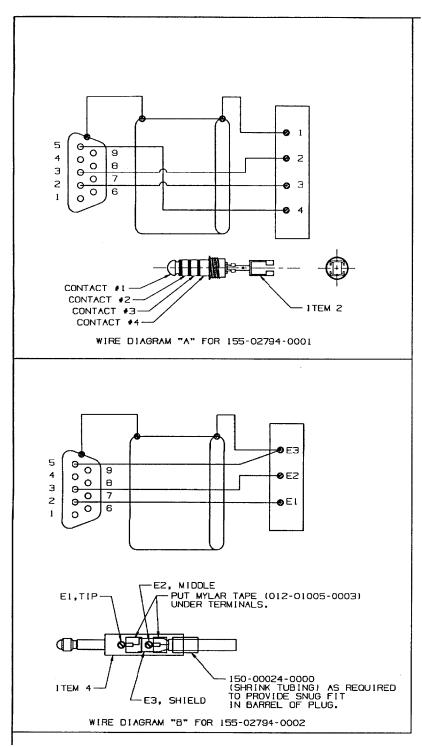
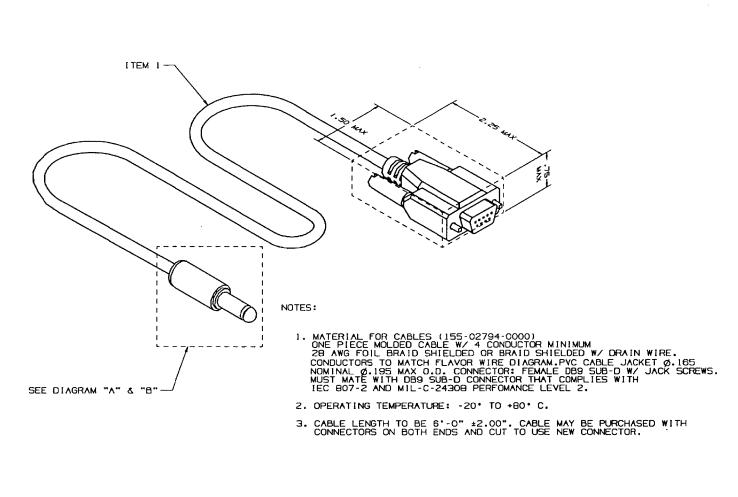


FIGURE 2-5 KC 140 INTERCONNECT (Sheet 5 of 5)





155-02794-0000 R1 COMPUTER CABLE ASSEMBLY

FIGURE 2-6 KC140 COMPUTER CABLE ASSEMBLY (Dwg No 155-02794-0000/0002, Rev 1) (Sheet 1 of 1)

6										
<u> AlliedSignal</u>	STA	STATUS			REVISION HISTORY		REVISION HISTORY			
3	SHT	REV	REV NO	SHEETS	DESCRIPTION	REV NO	SHEETS	DESCRIPTION		
	1	1	IR	1-5	FIRST RELEASE.					
	2	1			APPVD:DAVE_KRIZ DATE:7-12-96					
	3	IR .	1	1	DEVICION HISTORY					
ied (5	1 IR	'	2	REVISION HISTORY. DELETED (1 REVOLUTION PER MINUTE) FROM NOTE 7. REVISED NOTE 2.					
AlliedSignal Avionics Inc. Olathe, Kaneae 88082		111		4	REVISED NOTE 2. REVISED NOTE 2. APPVD: DATE:					
Z Z										
NAME										
DIUIC										
ž A										
ISULC										
CLUTCH ADJUSTMENT										
00										
DRN: LAH										
보										
DATE 7-96										
NUMBER 159-08155-5006										
3155-										
5006										
→ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \										
THE SHA										
T REV										
7 (0										
SCALE										
<u>₹</u>										
SHT DESCRIPTION REVISION H										
ESCRIPTION REVISION HISTORY										
IH NO										
STOR										
~										
b	E SE	SHT REV REFLECTS REVISION LEVEL OF								
IRPOF	ET W	문 도 도 도								
일시	AS L	SION								
KAP 140 CAD : 11.	AST (
KAP 140 AIRPORT CAD : 11309-01	NA ¥	FCTS								
[-@1	E]								
				1			-	ı		

FIGURE 2-7 CLUTCH ADJUSTMENT (Dwg No 159-08155-5006, Rev 1) (Sheet 1 of 5)

Revision 6, Oct 2002 CS:00991I06.IDU

KM 275 - CABLE CAPSTAN - CLUTCH ADJUSTMENT

- 1. CAPSTAN TORQUE SETTINGS ARE ADJUSTABLE AND MUST BE SET PRIOR TO INSTALLATION. THE FIXTURE AND TOOLS REQUIRED TO PERFORM THESE ADJUSTMENTS ARE LISTED IN SECTION 1 OF THE INSTALLATION MANUAL.
- 2. CHECK THE INSTALLATION MANUAL TO DETERMINE THE SERVO MOUNT PART NUMBER AND SETTING REQUIRED FOR EACH AXIS OF THE AIRCRAFT. THE SERVO MOUNT PART NUMBERS ARE LISTED WITH THE AUTOPILOT EQUIPMENT. THE CLUTCH ADJUSTMENT SETTINGS ARE LISTED IN A SEPARATE TABLE.
- 3. REMOVE THE CABLE GUARD FROM THE CAPSTAN .
- 4. PLACE THE ADAPTER TOOL OVER THE CAPSTAN AND INSERT THE POSITIONING PIN (FROM THE STRAIGHT-UP POSITION) TO SECURE THE ADAPTER TOOL.
- 5. INSERT A TORQUE WRENCH (SNAP-ON TEP-6FUA OR EQUIVALENT) AS SHOWN ON SHEET 3 OF THIS DRAWING.
- 6. APPLY 28 VDC (1 AMP MAX.) POWER TO THE TEST STAND JACKS.
- 7. USING THE CAPSTAN ROTATION SWITCH ON THE TEST STAND, TURN THE TEST STAND MOTOR ON IN THE CLOCKWISE DIRECTION AND READ THE TORQUE ON THE WRENCH REPEAT THIS STEP IN THE COUNTERCLOCKWISE DIRECTION.

THE DESIRED TORQUE READING IS THE AVERAGE OF THE MAXIMUM AND MINIMUM READINGS OBTAINED FROM THE CLOCKWISE AND COUNTERCLOCKWISE ROTATIONS.

THIS TEST SHOULD BE REPEATED THREE (3) TIMES IN EACH DIRECTION AND THEN AVERAGE THE SIX (6) READINGS TO DETERMINE THE FINAL

- 8. IF THE LEVEL DETERMINED FALLS BELOW THE DESIRED VALUE, ROTATE THE CLUTCH ADJUST NUT CLOCKWISE. IF THE LEVEL DETERMINED FALLS ABOVE THE DESIRED VALUE, ROTATE THE CLUTCH ADJUST NUT COUNTERCLOCKWISE. AFTER AN ADJUSTMENT, REPEAT
- 9. RECORD THE SLIP CLUTCH TORQUE READING, AIRCRAFT TYPE, AXIS AND DATE ON THE DECAL AFFIXED TO THE SERVO MOUNT BODY.

FIGURE 2-7 CLUTCH ADJUSTMENT (Dwg No 159-08155-5006, Rev 1) (Sheet 2 of 5)

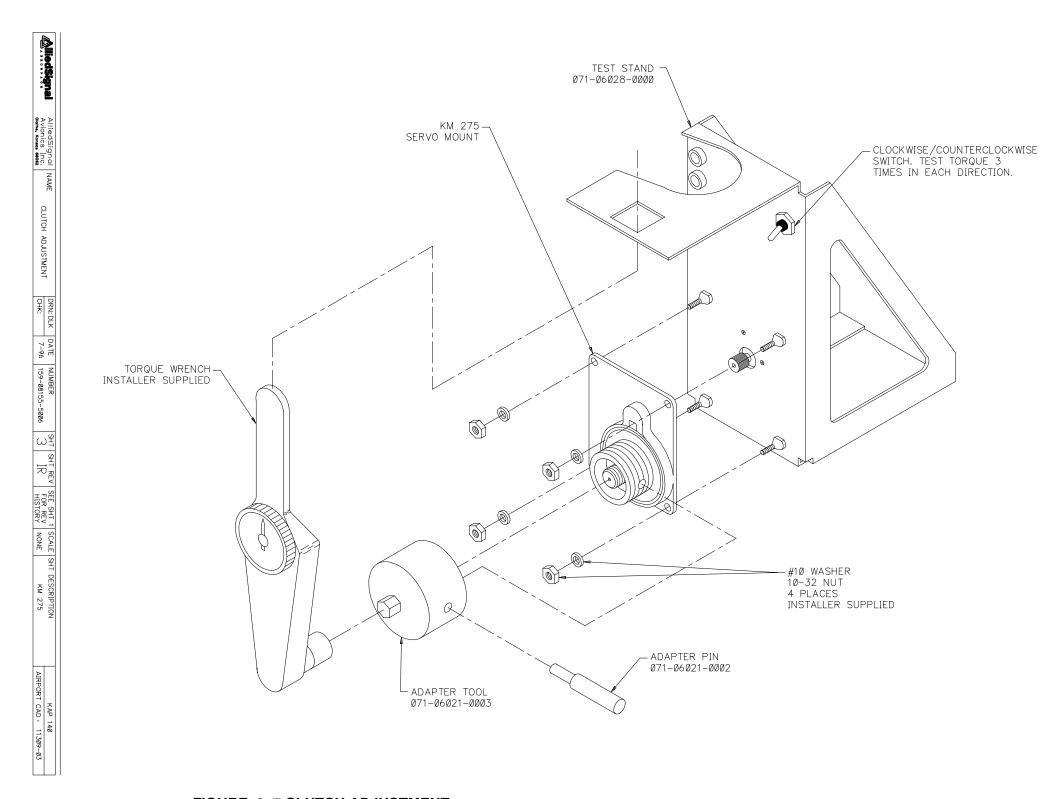


FIGURE 2-7 CLUTCH ADJUSTMENT (Dwg No 159-08155-5006, Rev IR) (Sheet 3 of 5)

.lliedSign .vionics ir

NAME

CH ADJUSTMENT

LAH DATE NI 7-96 1 KM 277 - CHAIN CAPSTAN - CLUTCH ADJUSTMENT

- 1. THE FIXTURE AND TOOLS REQUIRED TO PERFORM THESE ADJUSTMENTS ARE LISTED IN SECTION 1 OF THE INSTALLATION MANUAL.
- 2. CHECK THE INSTALLATION MANUAL TO DETERMINE THE SERVO MOUNT PART NUMBER AND SETTING REQUIRED FOR EACH AXIS OF THE AIRCRAFT. THE SERVO MOUNT PART NUMBERS ARE LISTED WITH THE AUTOPILOT EQUIPMENT. THE CLUTCH ADJUSTMENT SETTINGS ARE LISTED IN A SEPARATE TABLE.
- 3. REMOVE THE CLUTCH-CAPSTAN ASSEMBLY FROM THE CAPSTAN PLATE. SEE SHEET 5 DF THIS DRAWING.
- 4. CLAMP THE CLUTCH-GEAR ASSEMBLY IN A BENCH VISE THAT HAS RUBBER-COVERED GRIPS (TO PROTECT THE ROLLER CHAIN SPROCKET TEETH).
- 5. PLACE THE GEAR ADAPTER 071-06018-0006 ON THE CLUTCH ASSEMBLY. SEE SHEET 5 OF THIS DRAWING.
- 6. USING A TORQUE WRENCH (SNAP-ON TEP-6FUA OR EQUIVALENT) WITH A 3/4 INCH SOCKET ATTACHED, CHECK THE SETTING BY ROTATING THE TORQUE WRENCH (ATTACHED TO THE GEAR ADAPTER) AND READING THE TORQUE REQUIRED TO SLIP THE CLUTCH IN BOTH THE CLOCKWISE AND COUNTERCLOCKWISE DIRECTIONS.

NOTE

THE TORQUE READING DESIRED IS THE CONTINUOUS ROTATION TORQUE. THIS TEST SHOULD BE REPEATED THREE (3) TIMES CLOCKWISE AND (3) TIMES COUNTERCLOCKWISE THEN AVERAGE THE SIX (6) READINGS TO DETERMINE THE FINAL TORQUE READING.

- 7. IF THE LEVEL DETERMINED FALLS BELOW THE DESIRED VALUE, ROTATE THE CLUTCH ADJUST NUT CLOCKWISE. IF THE LEVEL DETERMINED FALLS ABOVE THE DESIRED VALUE, ROTATE THE CLUTCH ADJUST NUT COUNTERCLOCKWISE. AFTER AN ADJUSTMENT, REPEAT THE TORQUE TEST.
- 8. RECORD THE SLIP CLUTCH READING, AIRCRAFT TYPE, AXIS AND DATE ON THE DECAL AFFIXED TO THE SERVO MOUNT BODY.

FIGURE 2-7 CLUTCH ADJUSTMENT (Dwg No 159-08155-5006, Rev 1) (Sheet 4 of 5)

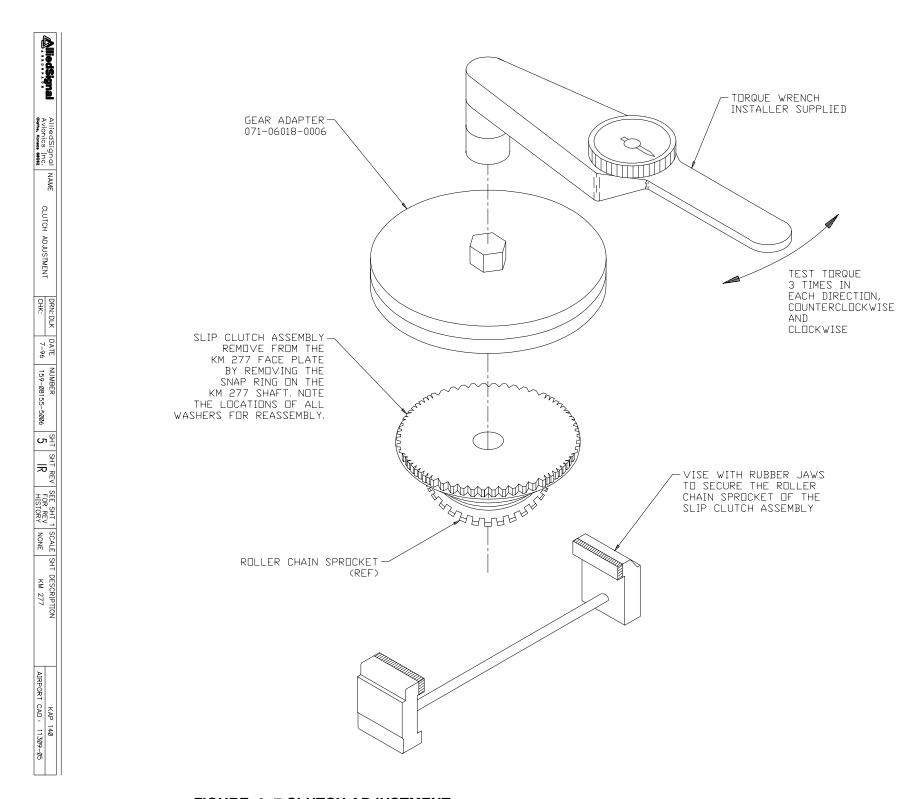


FIGURE 2-7 CLUTCH ADJUSTMENT (Dwg No 159-08155-5006, Rev IR) (Sheet 5 of 5)

SECTION 3.0 OPERATION

3.1 GENERAL

Refer to the STC installation manual of the particular aircraft which the system is installed for operating procedures or the Flight Manual Supplement of the particular aircraft.

TSO APPENDIX RTCA DO-160C ENVIRONMENTAL QUALIFICATION FORMS

RTCA/DO 160C

ENVIRONMENTAL QUALIFICATION FORM

NOMENCLATURE:	KC 140 FLIGHT COMPUTER
PART NUMBER:	065-00176-2602
	065-00176-2603
	065-00176-2704
	065-00176-5302
	065-00176-7802
	065-00176-5402
	065-00176-5403
	065-00176-5504
	065-00176-7702
	065-00176-7703
	065-00176-7904
TSO NUMBER:	C9c
MANUFACTURER'S SPECIFICATION:	MPS 004-02036-4001
MANUFACTURER:	Honeywell International Inc.
ADDRESS:	23500 West 105th Street
	OLATHE, KS 66061

U.S.A

Section	Condition	Category	Description
4.0	Temp/alt	A2/B2/C1	Decompression, -45 deg to +70 deg C, 35,000 feet
4.5.4	Inflt cool loss	-	No forced cooling
5.0	Temp var	В	5 deg/min
6.0	Humidity	A	Standard
7.0	Shock		Operational shock, crash safety
8.0	Vibration	MSB	Instrument panel, single engine (see notes)
9.0	Explosion	X	Not tested
10.0	Waterproof	X	Not tested
11.0	Fluids	X	Not tested
12.0	Sand & dust	X	Not tested
13.0	Fungus	X	Not tested
14.0	Salt Spray	X	Not tested
15.0	Magnetic	Z	Less than 0.3 meter
16.0	Power input	Z	Battery may be on line (for 28V installation)
16.0	Power input	В	Battery on line (for 14V installation) (see notes)
17.0	Voltage spike	A	High degree of protection
18.0	Audio freq	Z	Battery may be on line (for 28V installation)
18.0	Audio freq	В	Battery on line (for 14V installation) (see notes)
19.0	Ind sig susc	$^{\circ}\mathbf{A}$	Interference free
20.0	RF susc	U	20V/meter (see notes)
21.0	RF emission	\mathbf{Z}^{-1}	Interference level
22.0	Lightning Ind	A3XX	Moderate environment (see notes)
23.0	Lightning Dir	X	Not tested
24.0	Icing	X	Not tested

Honeywell International, Inc.

KPN 004-02036-4803 Revision B Page 1 of 3

Olathe, KS 66061

RTCA/DO 160C

ENVIRONMENTAL QUALIFICATION FORM

Notes:

1. Vibration Critical Frequencies:

The following critical frequencies are mechanical resonances of the unit under test that have peak acceleration amplitudes greater than twice the input acceleration amplitude. There were no observed changes in performance of the unit under test.

Vertical Longitudinal (top to bottom) (front to back)	Lateral (side to side)
76 TO 160HZ 327 TO 492HZ	199 TO 495HZ
204 TO 228HZ	
291 TO 351HZ	
429 TO 445HZ	
480 TO 500HZ	

There were no observed changes in the above resonant frequencies.

2. Pin Injection Testing:

The unit interconnect pins were tested to category A3. The following pins, however, were qualified with additional notes as follows:

P1402-49 Audio Load

Qualified to waveform 4 with a 500 ohm resistance placed in series with the generator.

Qualified to waveform 3 without any resistor in series with the generator.

3. RF Susceptibility:

The effects on KAP 140 computer were present between the frequencies of 140 Mhz and 300 Mhz. The maximum effect was to cause an offset of 0.6 g's in normal accelerometer output. The effect of this offset is documented in KAP 140 fault analysis document.

4. Power Input and Audio Frequency:

The KC 140 can not be designated as electrical equipment required to operate under emergency electrical system conditions in 14V applications. The operation of KC140 is not guaranteed for voltages less than 11V.

Honeywell International, Inc.

KPN 004-02036-4803 Revision B

Olathe, KS 66061

Page 2 of 3

RTCA/DO 160C

ENVIRONMENTAL QUALIFICATION FORM

REVISION	CHAN	GE ORDER NO.	DATE	ATE	
-	PRN#	146072	July 8, 1998		
\mathbf{A}	ECO#	712231	March 18, 2002		
В	ECO#	719656	October 8, 2002		

RTCA/DO 160C

ENVIRONMENTAL QUALIFICATION FORM

NOMENCLATURE: KC 140 FLIGHT COMPUTER

PART NUMBER: 065-00176-5001 065-00176-7501

045 00174 **5**101

065-00176-5101 065-00176-7601

TSO NUMBER: C9c

MANUFACTURER'S SPECIFICATION: MPS 004-02036-4000

MANUFACTURER: ALLIEDSIGNAL AVIONICS INC

ADDRESS: 400 NORTH ROGERS RD.

OLATHE, KS 66062

U.S.A

Section	Condition	Category	Description
4.0	Temp/alt	A2/B2/C1	Decompression, -45 deg to +70 deg C, 35,000 feet
4.5.4	Inflt cool loss	-	No forced cooling
5.0	Temp var	В	5 deg/min
6.0	Humidity	A	Standard
7.0	Shock	-	Operational shock, crash safety
8.0	Vibration	MSB	Instrument panel, single engine (see notes)
9.0	Explosion	X	Not tested
10.0	Waterproof	X	Not tested
11.0	Fluids	X	Not tested
12.0	Sand & dust	X	Not tested
13.0	Fungus	X	Not tested
14.0	Salt Spray	X	Not tested
15.0	Magnetic	Z	Less than 0.3 meter
16.0	Power input	Z	Battery may be on line (for 28V installation)
16.0	Power input	В	Battery on line (for 14V installation)
17.0	Voltage spike	Α	High degree of protection
18.0	Audio freq	ZB	Battery may be on line
19.0	Ind sig susc	Α	Interference free
20.0	RF susc	U	20V/meter (see notes)
21.0	RF emission	Z	Interference level
22.0	Lightning Ind	A3XX	Moderate environment (see notes)
23.0	Lightning Dir	X	Not tested
24.0	Icing	X	Not tested

AlliedSignal Avionics Inc. (d.b.a.)
AlliedSignal Electronic & Avionics Systems
Olathe, KS 66062

KPN 004-02036-4801 Revision AA Page 1 of 3

RTCA/DO 160C

ENVIRONMENTAL QUALIFICATION FORM

Notes:

1. Vibration Critical Frequencies:

The following critical frequencies are mechanical resonances of the unit under test that have peak acceleration amplitudes greater than twice the input acceleration amplitude. There were no observed changes in performance of the unit under test.

Vertical (top to bottom)	Longitudinal (front to back)	Lateral (side to side)
78 TO 179HZ 230 TO 236HZ 259 TO 272HZ 293 TO 495HZ	320 TO 475HZ	194 TO 406HZ

There were no observed changes in the above resonant frequencies.

2. Pin Injection Testing:

The unit interconnect pins were tested to category A3. The following pins, however, were qualified with additional notes as follows:

P1402-49 Audio Load

Qualified to waveform 4 with a 500 ohm resistance placed in series with the generator.

Qualified to waveform 3 without any resistor in series with the generator.

3. RF Susceptibility:

The effects on KAP 140 computer were present between the frequencies of 140 Mhz and 300 Mhz. The maximum effect was to cause an offset of 0.6 g's in normal accelerometer output. The effect of this offset is documented in KAP 140 fault analysis document.

RTCA/DO 160C

ENVIRONMENTAL QUALIFICATION FORM

REVISION	CHANGE ORDER NO.	DATE
0	Original Issue	August 6, 1996
1	117311	August 21, 1996
7	117977	September 12, 1996
3	125366	March 17, 1997
4	125639	March 20, 1997
T 5	126986	May 2, 1997
AA	135888	January 7, 1998

RTCA/DO-160C ENVIRONMENTAL QUALIFICATION FORM

NOMENCLATURE: KS 270C Servo Actuator

PART NUMBER: 065-00178-0100, 0200, 0300

065-00178-2100, 2200

065-00178-2300, 2400, 2500

TSO NUMBER: C9c

MANUFACTURER'S SPECIFICATION: 004-02037-4000

MANUFACTURER: AlliedSignal Inc.

MANUFACTURER'S ADDRESS: 400 N. ROGERS ROAD

OLATHE, KS 66062, USA

CONDITIONS	SECTION	CONDUCTED TESTS
TEMPERATURE AND ALTITUDE	4.0	CATEGORIES A2/F2
INFLIGHT COOLING LOSS	4.5	NOT TESTED
TEMPERATURE VARIATION	5.0	CATEGORY B
HUMIDITY	6.0	CATEGORY A
SHOCK	7.0	OPERATIONAL SHOCK,
	•	CRASH SAFETY
VIBRATION	8.0	CATEGORIES L, M (SEE NOTE)
EXPLOSION	9.0	CATEGORY E1
WATERPROOFNESS	10,0	CATEGORY X (NOT TESTED)
FLUID SUSCEPTIBILITY	11.0	CATEGORY X (NOT TESTED)
SAND AND DUST	12.0	CATEGORY X (NOT TESTED)
FUNGUS	13.0	CATEGORY X (NOT TESTED)
SALT SPRAY	14.0	CATEGORY X (NOT TESTED)
MAGNETIC EFFECT	15.0	CATEGORY A
POWER INPUT	16.0	CATEGORY B
VOLTAGE SPIKE	17.0	CATEGORIES A/B
AUDIO FREQ COND SUSCEPT	18.0	CATEGORY B
INDUCED SIGNAL SUSCEPTIBILITY	19.0	CATEGORY A
RADIO FREQ SUSCEPTIBILITY	20.0	CATEGORY U
RADIO FREQUENCY EMISSION	21.0	CATEGORY Z
LIGHTNING IND TRANS SUSCEPT	22.0	CATEGORY A3XX
LIGHTNING DIRECT EFFECTS	23.0	CATEGORY X (NOT TESTED)
ICING	24.0	CATEGORY A

NOTE: Vibration Critical Frequencies are listed on page 2.

AlliedSignal Inc. AUTHORIZED PRINT

004-02037-4800 REVISION AC PAGE 1 OF 3

The following critical frequencies are mechanical resonances of the unit under test that have peak acceleration amplitudes greater than twice the input acceleration amplitude. There were no observed changes in the performance of the unit under test.

Vertical
(top to bottom)Longitudinal
(front to back)Lateral
(side to side)85 Hz - 87 Hz312 Hz - 447 Hz300 Hz - 351 Hz

There were no observed changes in the above resonant frequencies.

AlliedSignal Inc.

004-02037-4800 REVISION AC PAGE 2 OF 3

RTCA/DO-160C ENVIRONMENTAL QUALIFICATION FORM

REVISION HISTORY

REVISION	CHANGE ORDER NO.	DATE
0	Original Issue	05/31/96
1	116692	08/05/96
2	117105	08/18/96
3	124005	01/31/97
AA	135767	01/06/98
AB	137252	02/03/98
AC	143715	06/29/98

AlliedSignal Inc.

004-02037-4800 REVISION AC PAGE 3 OF 3

RTCA/DO-160C ENVIRONMENTAL QUALIFICATION FORM

NOMENCLATURE: KS 271C Servo Actuator

PART NUMBER: 065-00179-0100,0200,0300,

065-00179-0400, 0500, 0600

TSO NUMBER: C9c

MANUFACTURER'S SPECIFICATION: 004-02038-4000

MANUFACTURER: AlliedSignal Avionics Inc.

A wholly-owned subsidiary

of AlliedSignal Inc.

MANUFACTURER'S ADDRESS: 400 N. ROGERS ROAD

OLATHE, KS 66062, USA

CONDITIONS	SECTION	CONDUCTED TESTS
TEMPERATURE AND ALTITUDE	4.0	CATEGORIES A2/F2
INFLIGHT COOLING LOSS	4.5	NOT TESTED
TEMPERATURE VARIATION	5.0	CATEGORY B
HUMIDITY	6.0	CATEGORY A
SHOCK	7.0	OPERATIONAL SHOCK,
		CRASH SAFETY
VIBRATION	8.0	CATEGORIES L, M (SEE NOTE)
EXPLOSION	9.0	CATEGORY E1
WATERPROOFNESS	10.0	CATEGORY X (NOT TESTED)
FLUID SUSCEPTIBILITY	11.0	CATEGORY X (NOT TESTED)
SAND AND DUST	12.0	CATEGORY X (NOT TESTED)
FUNGUS	13.0	CATEGORY X (NOT TESTED)
SALT SPRAY	14.0	CATEGORY X (NOT TESTED)
MAGNETIC EFFECT	15.0	CATEGORY A
POWER INPUT	16.0	CATEGORY B
VOLTAGE SPIKE	17.0	CATEGORIES A/B
AUDIO FREQ COND SUSCEPT	18.0	CATEGORY B
INDUCED SIGNAL SUSCEPTIBILITY	19.0	CATEGORY A
RADIO FREQ SUSCEPTIBILITY	20.0	CATEGORY U
RADIO FREQUENCY EMISSION	21.0	CATEGORY Z
LIGHTNING IND TRANS SUSCEPT	22.0	CATEGORY A3XX
LIGHTNING DIRECT EFFECTS	23.0	CATEGORY X (NOT TESTED)
ICING	24.0	CATEGORY A

NOTE: Vibration Critical Frequencies are listed on page 2.

AUTHORIZED PRINT

AlliedSignal Avionics Inc.

004-02038-4800 REVISION AC PAGE 1 OF 3

The following critical frequencies are mechanical resonances of the unit under test that have peak acceleration amplitudes greater than twice the input acceleration amplitude. There were no observed changes in the performance of the unit under test.

Vertical Longitudinal Lateral

(top to bottom) (front to back) (side to side)

85 Hz - 87 Hz 312 Hz - 447 Hz 300 Hz - 351 Hz

There were no observed changes in the above resonant frequencies.

AlliedSignal Avionics Inc.

004-02038-4800 REVISION AC PAGE 2 OF 3

RTCA/DO-160C ENVIRONMENTAL QUALIFICATION FORM

REVISION HISTORY

REVISION	CHANGE ORDER NO.	DATE
0	Original Issue	06/10/96
1	116692	08/05/96
2	117105	08/18/96
3	124005	01/31/97
4	124581	02/18/97
ÁΑ	135767	01/06/98
AB	137252	02/03/98
AC	139720	. 03/31/98

AlliedSignal Avionics Inc.

004-02038-4800 REVISION AC PAGE 3 OF 3

RTCA/DO-160C Change Notices 1, 2, and 3 ENVIRONMENTAL QUALIFICATION FORM

NOMENCLATURE:

KS 272C Servo Actuator

PART NUMBER:

065-00180-0400, 1400, 2700, 3500

065-00180-0600, 0800

TSO NUMBER:

C9c

MANUFACTURER'S SPECIFICATION:

004-02039-4000

MANUFACTURER:

Honeywell International Inc.

MANUFACTURER'S ADDRESS:

OLATHE, KS 66061, USA

CONDITIONS	SECTION	CONDUCTED TESTS
TEMPERATURE AND ALTITUDE	4.0	CATEGORIES A2/F2
INFLIGHT COOLING LOSS	4.5	NOT TESTED
TEMPERATURE VARIATION	5.0	CATEGORY B
HUMIDITY	6.0	CATEGORY A
SHOCK	7.0	OPERATIONAL SHOCK,
		CRASH SAFETY
VIBRATION	8.0	CATEGORIES L, M (SEE NOTE)
EXPLOSION	9.0	CATEGORY E1
WATERPROOFNESS	10.0	CATEGORY X (NOT TESTED)
FLUID SUSCEPTIBILITY	11.0	CATEGORY X (NOT TESTED)
SAND AND DUST	12.0	CATEGORY X (NOT TESTED)
FUNGUS	13.0	CATEGORY X (NOT TESTED)
SALT SPRAY	14.0	CATEGORY X (NOT TESTED)
MAGNETIC EFFECT	15.0	CATEGORY A
POWER INPUT	16.0	CATEGORY B
VOLTAGE SPIKE	17.0	CATEGORIES A/B
AUDIO FREQ COND SUSCEPT	18.0	CATEGORY B
INDUCED SIGNAL SUSCEPTIBILITY	19.0	CATEGORY A
RADIO FREQ SUSCEPTIBILITY	20.0	CATEGORY U
RADIO FREQUENCY EMISSION	21.0	CATEGORY Z
LIGHTNING IND TRANS SUSCEPT	22.0	CATEGORY A3XX
LIGHTNING DIRECT EFFECTS	23.0	CATEGORY X (NOT TESTED)
ICING	24.0	CATEGORY A

NOTE: Vibration Critical Frequencies are listed on page 2.

Honeywell International Inc.

004-02039-4800 REVISION AB PAGE 1 OF 3

The following critical frequencies are mechanical resonances of the unit under test that have peak acceleration amplitudes greater than twice the input acceleration amplitude. There was no observed changes in the performance of the unit under test.

Vertical	Longitudinal	Lateral
(top to bottom)	(front to back)	(side to side)
214 Hz - 310 Hz	74 Hz - 154 Hz	41 Hz - 160 Hz
	160 Hz - 191 Hz	472 Hz - 500 Hz
	255 Hz - 430 Hz	

There were no observed changes in the above resonant frequencies.

Honeywell International Inc.

004-02039-4800 REVISION AB PAGE 2 OF 3

RTCA/DO-160C ENVIRONMENTAL QUALIFICATION FORM

REVISION	CHANGE ORDER NO.	DATE
0	Original Issue	06/10/96
1	116692	08/05/96
2	117105	08/18/96
3	123691	01/23/97
4	124005	01/31/97
AA	139720	03/31/98
AB	172207	05/11/00

RTCA/DO 160C

ENVIRONMENTAL QUALIFICATION FORM

NOMENCLATURE:

KC 140 FLIGHT COMPUTER

PART NUMBER:

065-00176-5201

TSO NUMBER:

C9c

MANUFACTURER'S SPECIFICATION:

MPS 004-02036-4000

MANUFACTURER:

ALLIEDSIGNAL AVIONICS INC

ADDRESS:

400 NORTH ROGERS RD. OLATHE, KS 66062

U.S.A

Section	Condition	Category	Description
4.0	Temp/alt	A2/B2/C1	Decompression, -45 deg to +70 deg C, 35,000 feet
4.5.4	Inflt cool loss	-	No forced cooling
5.0	Temp var	В	5 deg/min
6.0	Humidity	A	Standard
7.0	Shock	-	Operational shock, crash safety
8.0	Vibration	MSB	Instrument panel, single engine (see notes)
9.0	Explosion	X	Not tested
10.0	Waterproof	X	Not tested
11.0	Fluids	X	Not tested
12.0	Sand & dust	X	Not tested
13.0	Fungus	X	Not tested
14.0	Salt Spray	X	Not tested
15.0	Magnetic	Z	Less than 0.3 meter
16.0	Power input	Z	Battery may be on line (for 28V installation)
16.0	Power input	В	Battery on line (for 14V installation)
17.0	Voltage spike	Α	High degree of protection
18.0	Audio freq	ZB	Battery may be on line
19.0	Ind sig susc	Α	Interference free
20.0	RF susc	U	20V/meter
21.0	RF emission	Z	Interference level
22.0	Lightning Ind	A3XX	Moderate environment (see notes)
23.0	Lightning Dir	X	Not tested
24.0	Icing	X	Not tested

AlliedSignal Avionics Inc. (d.b.a.)
AlliedSignal Electronic & Avionics Systems
Olathe, KS 66062

KPN 004-02036-4802 Revision -Page I of 3

RTCA/DO 160C

ENVIRONMENTAL QUALIFICATION FORM

Notes:

1. Vibration Critical Frequencies:

The following critical frequencies are mechanical resonances of the unit under test that have peak acceleration amplitudes greater than twice the input acceleration amplitude. There were no observed changes in performance of the unit under test.

Vertical (top to bottom)	Longitudinal (front to back)	Lateral (side to side)
75 TO 172 HZ 202 TO 252 HZ 265 TO 275 HZ 312 TO 384 HZ 403 TO 471 HZ 476 TO 500 HZ	304 TO 433 HZ	158 TO 444 HZ 464 TO 500 HZ

There were no observed changes in the above resonant frequencies.

2. Pin Injection Testing:

The unit interconnect pins were tested to category A3. The following pins, however, were qualified with additional notes as follows:

P1402-49 Audio Load

Qualified to waveform 4 with a 500 ohm resistance placed in series with the generator.

Qualified to waveform 3 without any resistor in series with the generator.

RTCA/DO 160C

ENVIRONMENTAL QUALIFICATION FORM

REVISION	CHANGE ORDER NO.	DATE
-	PRN # 135893	January 7, 1998

RTCA/DO-160C

ENVIRONMENTAL QUALIFICATION FORM

NOMENCLATURE: KCM 100 CONFIGURATION MODULE

PART NUMBER: 071-00073-5000

TSO NUMBER: C113, C9c, C52a, C129, C52b

MANUFACTURER'S SPECIFICATION: MPS 004-00950-0000

MANUFACTURER: ALLIEDSIGNAL INC.

ADDRESS: ONE TECHNOLOGY CENTER

23500 W. 105TH STREET OLATHE, KS 66061

USA

CONDITIONS	PARA	CONDUCTED TESTS
TEMPERATURE AND ALTITUDE	4.0	CATEGORY A2 and F2
TEMPERATURE VARIATION	5.0	CATEGORY B
HUMIDITY	6.0	CATEGORY A
SHOCK	7.0	TESTED PER DO-160C Para 7.2.1
VIBRATION	8.0	CATEGORIES M,N, and B
EXPLOSION	9.0	CATEGORY E1
WATERPROOFNESS	10.0	CATEGORY X (NOT TESTED)
FLUIDS SUSCEPTIBILITY	11.0	CATEGORY X (NOT TESTED)
SAND AND DUST	12.0	CATEGORY X (NOT TESTED)
FUNGUS	13.0	CATEGORY X (NOT TESTED)
SALT SPRAY	14.0	CATEGORY X (NOT TESTED)
MAGNETIC EFFECT	15.0	CLASS A
POWER INPUT	16.0	CATEGORY X (NOT TESTED)
VOLTAGE SPIKE CONDUCTED	17.0	CATEGORY X (NOT TESTED)
AUDIO FREQUENCY CONDUCTED	18.0	CATEGORY X (NOT TESTED)
SUSCEPTIBILITY		
INDUCED SIGNAL SUSCEPTIBILITY	19.0	CATEGORY A
RADIO FREQUENCY SUSCEPTIBILITY	20.0	CATEGORY T
RADIO FREQUENCY EMISSION	21.0	CATEGORY A
LIGHTNING INDUCED TRANSIENT	22.0	CATEGORY A3E3
SUSCEPTIBILITY		
LIGHTNING DIRECT EFFECTS	23.0	CATEGORY X (NOT TESTED)
ICING	24.0	CATEGORY X (NOT TESTED)

004-09104-0000 Revision AA Page 1 of 2

AUTHORIZED PRINT

RTCA DO-160C

ENVIRONMENTAL QUALIFICATION FORM

REVISION HISTORY

REVISION	CHANGE ORDER NO.	DATE
0	Original Issue	May 1993
1	ECO 98316	June 1993
2	ECO 98421	June 1993
3	ECO 113697	June 1996
AA	CO 148452	Oct. 1998

004-09104-0000 Revision AA Page 2 of 2

